

Entry, Descent, and Landing Systems Short Course

Subject: Aerodynamics & Aerothermodynamics

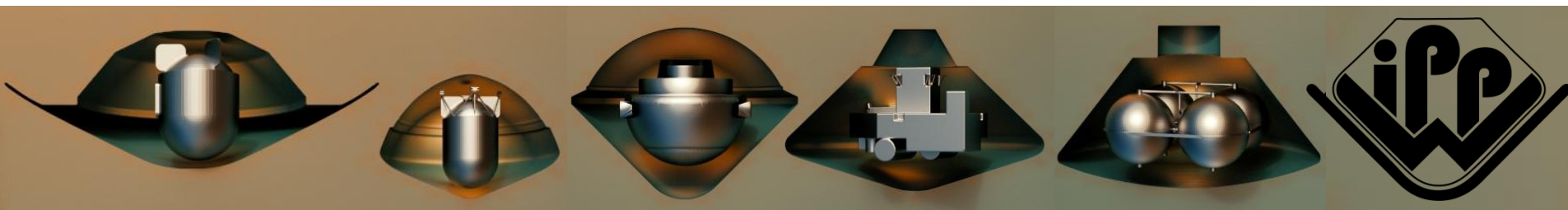
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NASA Langley Research Center

Mike Wright

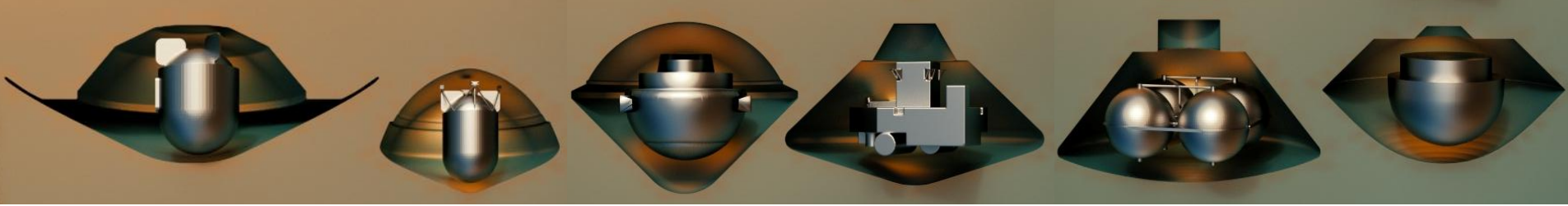
NASA Ames Research Center

sponsored by
International Planetary Probe Workshop 10
June 15-16, 2013
San Jose, California



Outline

- Aerodynamics
 - Introduction/History/Methods
 - Dynamic Stability
 - Aerothermodynamics
 - Introduction
 - Methods
 - Special Topics
 - Case Study: MSL
 - Q&A
-
- Material focuses on blunt rigid capsules



Aerodynamics



International Planetary Probe Workshop 10, EDL Short Course

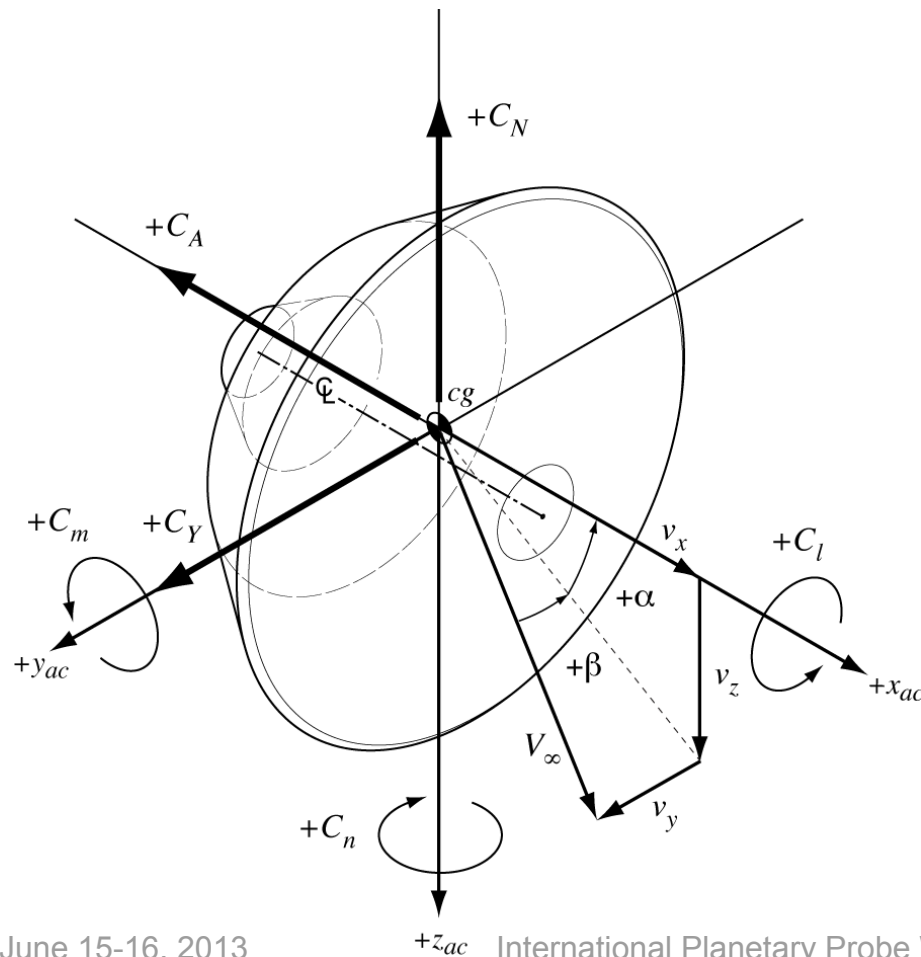


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Definitions

Aerodynamics = forces & moments imparted on the entry vehicle by the atmosphere

Primary EDL Needs: High C_D , Static stability ($dC_m/d\alpha < 0$)



Force Coefficient

$$C_X = \frac{F_X}{\frac{1}{2}\rho_\infty V_\infty^2 S_{ref}}$$

Moment Coefficient

$$C_x = \frac{M_x}{\frac{1}{2}\rho_\infty V_\infty^2 S_{ref} d_{ref}}$$

$$F = \int_{surface} (pressure + shear)$$

$$M = \int_{surface} (pressure + shear) \times (l - l_{ref})$$

Lift Coefficient $C_L = C_N \cos \alpha - C_A \sin \alpha$

Drag Coefficient $C_D = C_N \sin \alpha + C_A \cos \alpha$

Pitch and Yaw Damping Coefficients

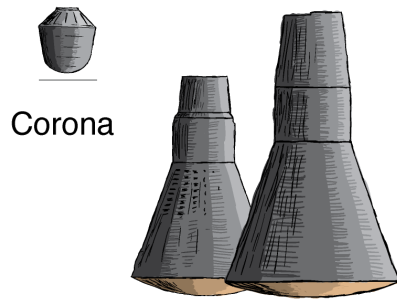
$$C_{m_q} + C_{m_{\dot{\alpha}}} = \frac{\partial C_m}{\partial \frac{qd_{ref}}{2V_\infty}} + \frac{\partial C_m}{\partial \frac{\dot{\alpha}d_{ref}}{2V_\infty}}$$

$$C_{n_r} - C_{n_{\dot{\beta}}} = \frac{\partial C_n}{\partial \frac{rd_{ref}}{2V_\infty}} - \frac{\partial C_n}{\partial \frac{\dot{\beta}d_{ref}}{2V_\infty}}$$

The Blunt-Body Arsenal* [2-37]

- EDL vehicles generally have blunt heatshields → high aerodynamic drag
- Other geometry drivers: packaging, stability, heating, science
- Backshells are generally selected to accommodate payload

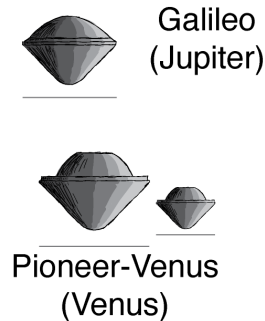
Sphere-Section



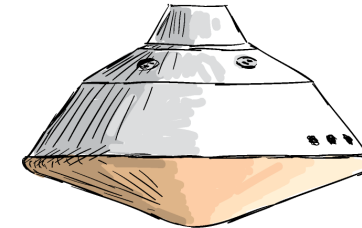
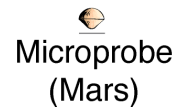
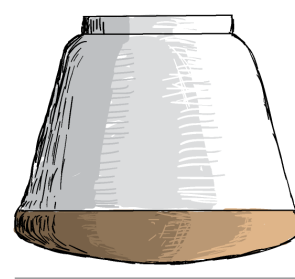
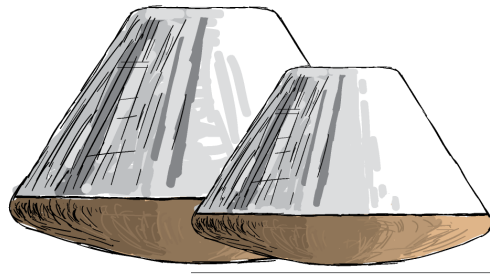
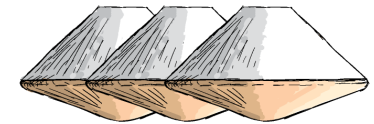
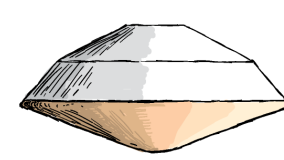
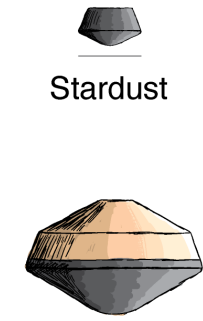
45° Sphere-Cone



60° Sphere-Cone



70° Sphere-Cone



4.5 meters

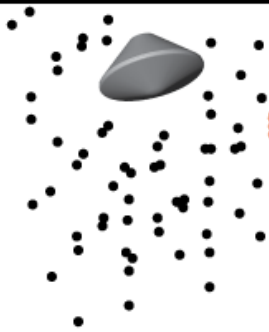
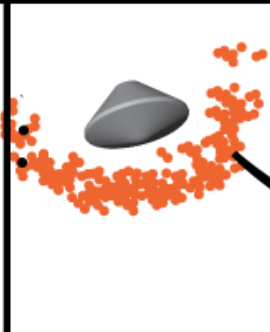
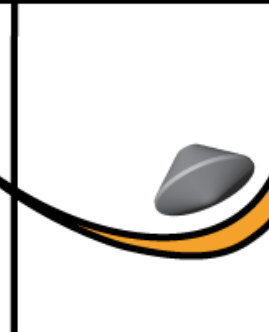





* Earth-entry unless noted. NASA or US Govt. mission unless noted.

Flight Regimes (e.g. MSL)

Each flight regime requires unique prediction methods

ENTRY
($V=5.8$ km/s)

Parachute Deploy
($V=0.5$ km/s)

	Rarefied	Transitional	Hypersonic	Supersonic	Supersonic Dynamics
Regime Definition	 <p>Knudsen > 1000</p>	 <p>$1000 > Kn > 0.001$</p>	 <p>$26.6 > Mach > 6$</p>	 <p>$6 > Mach > 1.5$</p>	 <p>$3.5 > Mach > 1.5$</p>
Data Source:	DAC DSMC code	DAC DSMC code	LAURA CFD (forebody)	LAURA (full aeroshell) w/ base correction	Ballistic Range Data
Characteristic Flow Physics	Molecules do not collide	Molecular collisions modeled, still not continuum flow	Chemically reacting flow Peak heating, Peak dynamic pressure	Wake aerodynamics contribute to capsule forces/moments	Unsteady wake introduces capsule dynamic instabilities
New Technical Challenges for MSL	 Uncertainties for Lifting Vehicle				
			 RCS interactions	 Higher L/D aerodynamics	
			Aero-load deformation Ablation shape change	Balance Mass Jettison	Lifting pitch/yaw damping

Newtonian Aerodynamics [38,39]

Newtonian method is an approximate method for estimating static aerodynamic coefficients

Newtonian method is more accurate for blunt bodies at hypersonic conditions

Diagram illustrating the Newtonian method for aerodynamics on a flat plate. The flow velocity is V_∞ , and the plate is at an angle θ to the flow. The mass flow rate through a control area A is $\dot{m} = \rho_\infty V_\infty A \sin \theta$. The normal component of the velocity is $V_N = V_\infty \sin \theta$, and the tangential component is V_T . The normal force F_N is shown acting perpendicular to the plate. The pressure coefficient C_p is derived as:

$$F = \dot{m} V_N = \rho_\infty A V_\infty^2 \sin^2 \theta$$

$$\frac{F}{A} = \rho_\infty V_\infty^2 \sin^2 \theta = p - p_\infty$$

$$C_p = \frac{p - p_\infty}{\frac{1}{2} \rho_\infty V_\infty^2} = \frac{2 V_N^2}{V_\infty^2} = 2 \sin^2 \theta$$

Lester Lees [40]: Updated Newtonian model replacing “2” with the maximum C_p based on Rayleigh Pitot equation (normal-shock relations), experiment or CFD.

Modified Newtonian “sine-squared law:”

$$C_p = C_{p_{max}} \sin^2 \theta$$

$$C_{p_{max}} = 1.839 \text{ for } \gamma = 1.4$$

Modified Newtonian Aerodynamics

From Lees [40]

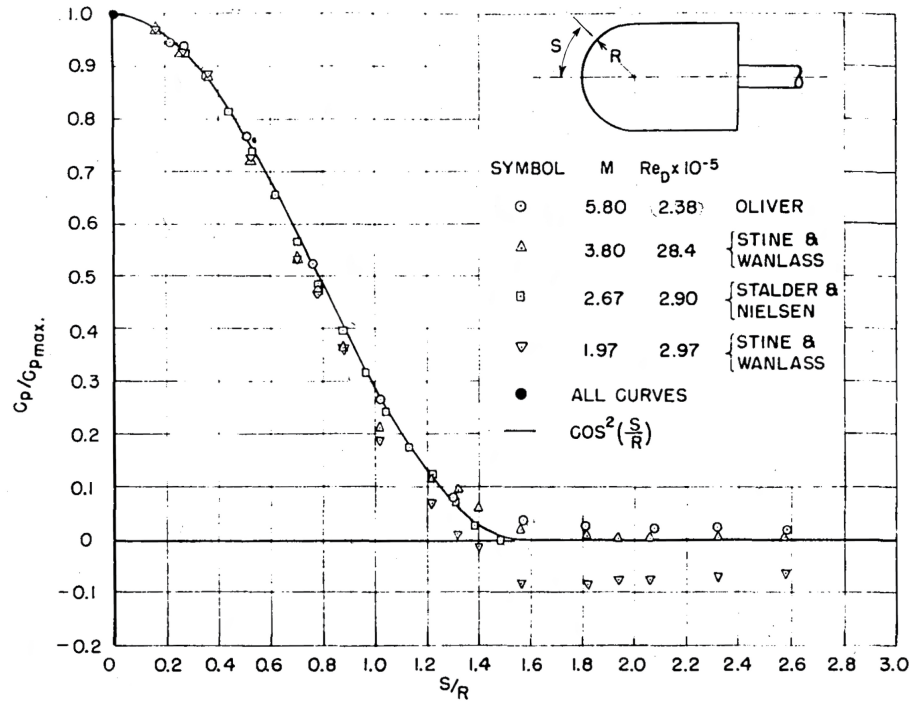


FIG.13—PRESSURE COEFFICIENT DISTRIBUTION ON SURFACE OF HEMISPHERE-CYLINDER AT VARIOUS MACH NUMBERS

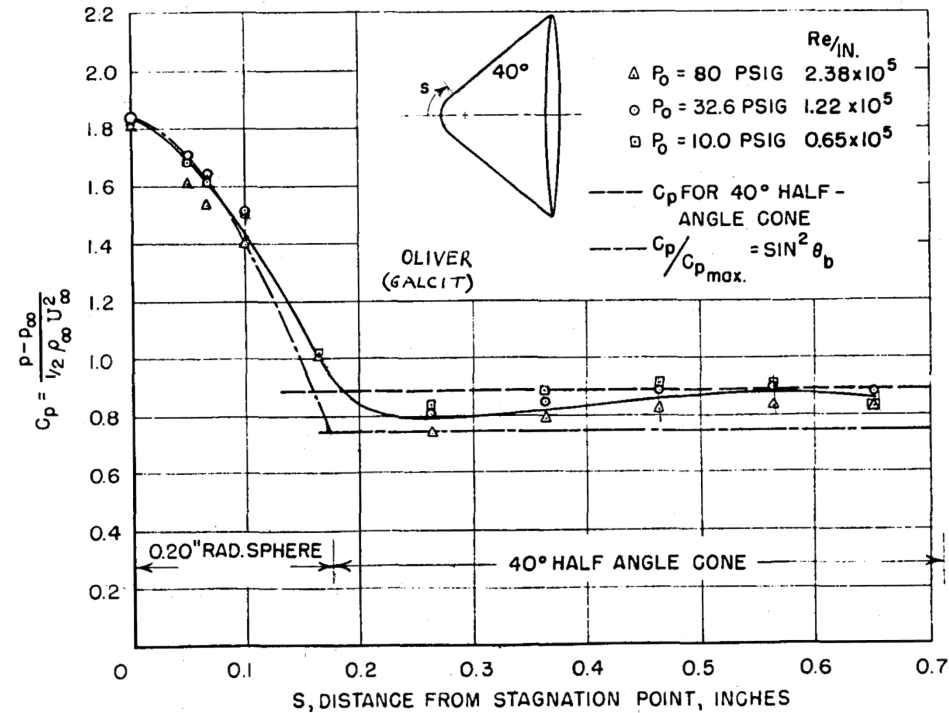
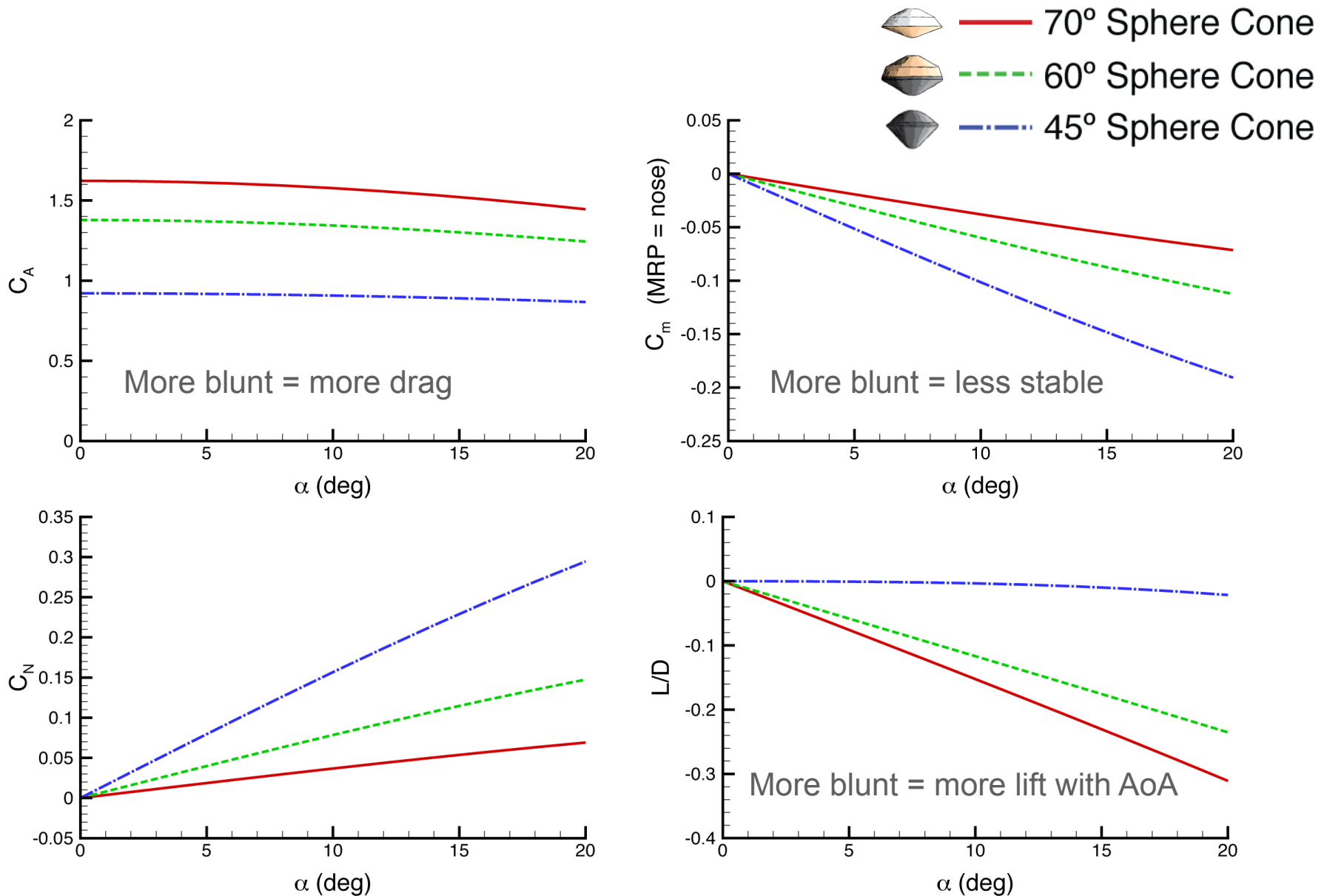


FIG.14—PRESSURE DISTRIBUTION OVER BLUNT CONE, $M_\infty = 5.8$, $\alpha = 0^\circ$

For hypersonic flows, local pressure is a function of the local surface angle relative to the flow

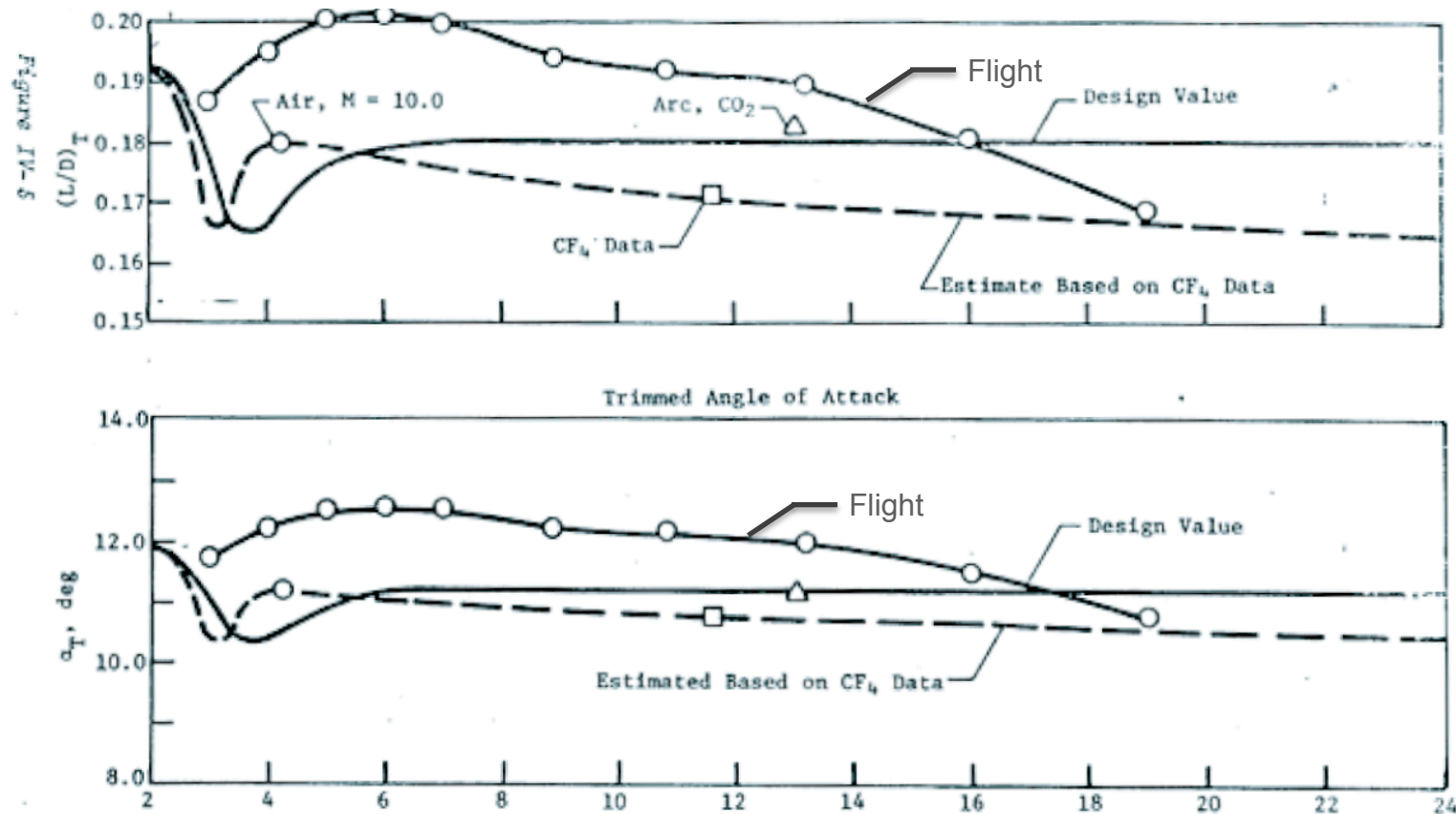
Blunt Body Aerodynamic Characteristics

Modified Newtonian, Air, Mach = 20

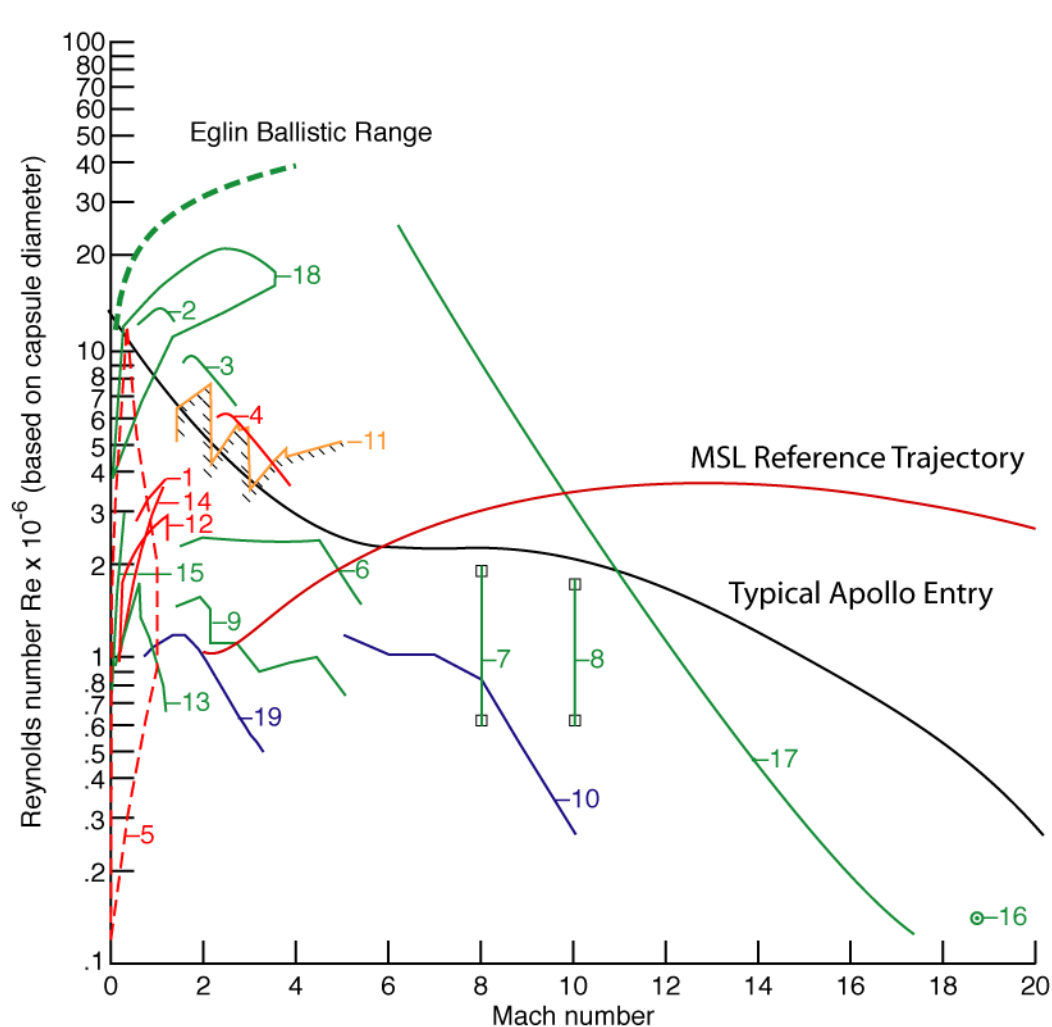


Viking Design vs. Flight Trim AOA and L/D [17]

- Viking was designed for $L/D = 0.18$ at a hypersonic trim AOA of 11 deg
- Aerodynamics were predicted from wind tunnel and ballistic range tests in air, CO_2 , CF_4
- VL1 and VL2 trim AOA (and L/D) were higher than the design values
 - Believed at the time to be caused by an off-nominal CG location and outgassing/ablation at the time, although low heat flux was experienced



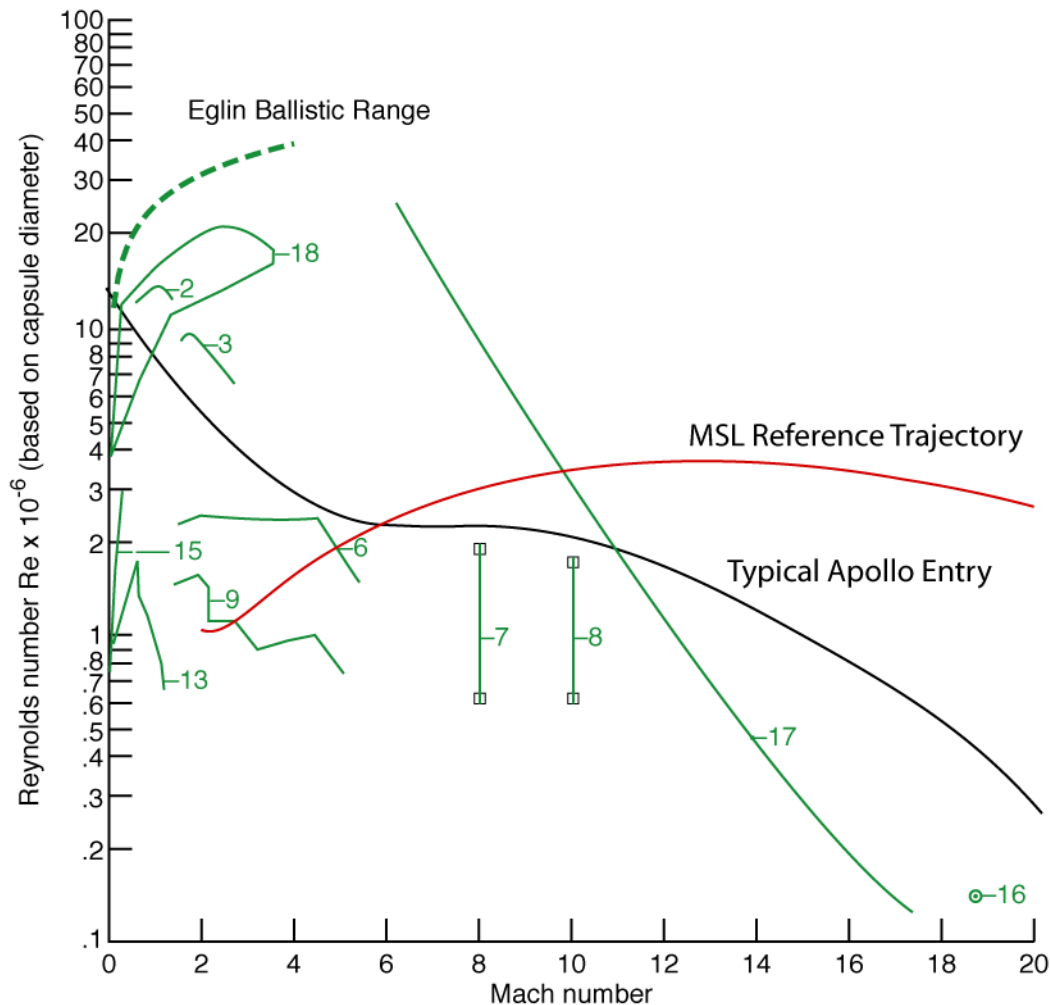
National Aerodynamic Experimental Facilities



1. Ames 14-Ft Transonic wind Tunnel (0.055 scale)
Ames Unitary Plan Wind Tunnels (0.105 scale)
2. 11 by 11 ft
3. 9 by 7 ft
4. 8 by 7 ft
5. Ames 12-Ft Pressure Tunnel (0.10 scale)
6. Arnold Engineering Development Center, von Karman Facility 50-In. Tunnel A (0.045 scale)
7. Arnold Engineering Development Center, von Karman Facility 50-In. Tunnel B (0.045 scale)
8. Arnold Engineering Development Center, von Karman Facility 50-In. Tunnel C (0.045 scale)
9. Jet Propulsion Laboratory 20-In. Supersonic Wind Tunnel (0.045 scale)
10. Jet Propulsion Laboratory 21-In. Hypersonic Wind Tunnel (0.02 scale)
11. Langley Unitary Plan Wind Tunnel (0.055 scale)
12. Langley 8-Ft Transonic Pressure Tunnel (0.055 scale)
13. Langley 16-Ft Transonic Dynamics Tunnel (0.08 scale)
14. Langley 16-Ft Transonic Wind Tunnel (0.085 scale)
15. North American Aerodynamics Laboratory 7- by 10-ft Low-Speed Wind Tunnel (0.105 scale)
16. Arnold Engineering Development Center, von Karman Facility 50-In. Hot-Shot II, Tunnel H (0.04 scale)
17. Cornell Aeronautical Laboratory 48-in. Shock Tunnel (0.05 scale)
18. North American Aviation 7- by 7-ft Trisonic Wind Tunnel (0.105 scale)
19. North American Aviation Supersonic Aerophysics Laboratory (0.02 scale)

From [10] NASA TN-D 3748, "Apollo Wind Tunnel Testing Program Historical Development of General Configurations"

National Aerodynamic Experimental Facilities



Ames Unitary Plan Wind Tunnels (0.105 scale)

2. 11 by 11 ft

3. 9 by 7 ft

6. Arnold Engineering Development Center, von Karman Facility 50-In. Tunnel A (0.045 scale)

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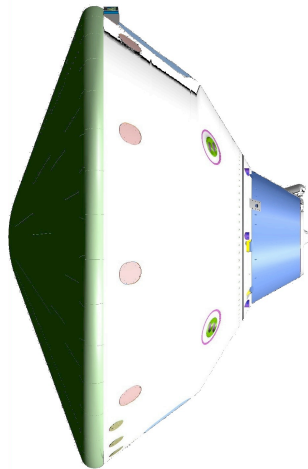
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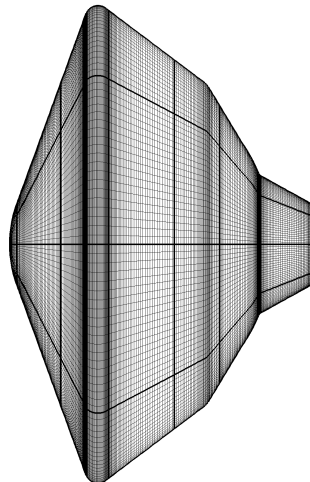
Computational Fluid Dynamics (CFD)

- Definition: Numerical solution of the fluid dynamic equations of motion
- The closing of wind tunnels & advancement of computers has pushed CFD to the forefront of aerothermodynamics prediction
 - CFD is a high-fidelity method of “simulating” flight conditions (esp. hypersonic)
- But, the resources required can be large (people, time, computers), especially for complex 3-D geometries
- Examples: LAURA (NASA Langley), DPLR (NASA Ames)

Vehicle Geometry



CFD Grid



Navier-Stokes Equations

Continuity equation $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{V}) = 0$

x Momentum $\rho \frac{Du}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z}$

y Momentum $\rho \frac{Dv}{Dt} = -\frac{\partial p}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z}$

z Momentum $\rho \frac{Dw}{Dt} = -\frac{\partial p}{\partial z} + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z}$

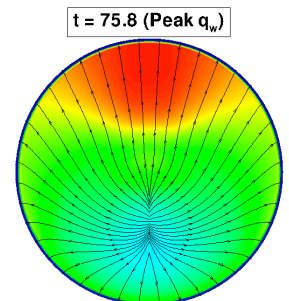
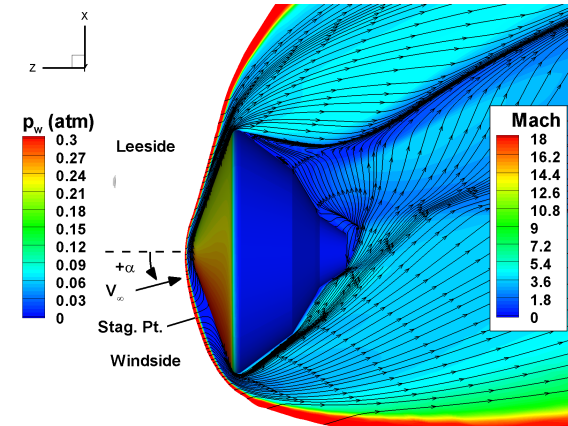
Energy

$$\rho \frac{D(e + V^2/2)}{Dt} = \rho \dot{q} + \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) - \nabla \cdot p \mathbf{V}$$

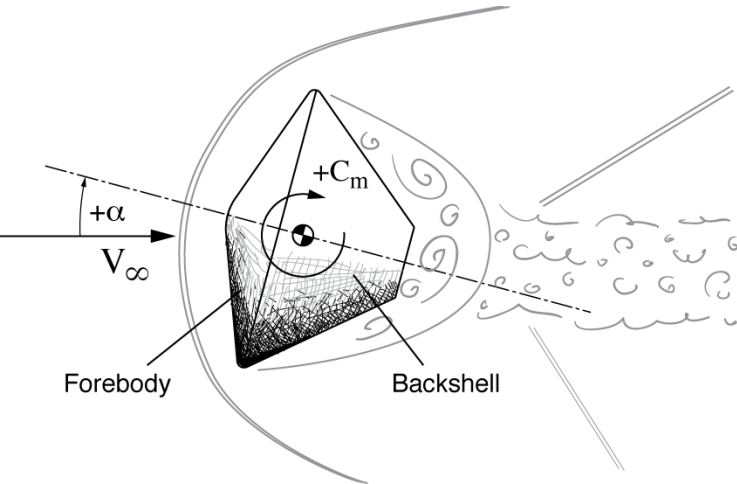
$$+ \frac{\partial (u\tau_{xx})}{\partial x} + \frac{\partial (u\tau_{yx})}{\partial y} + \frac{\partial (u\tau_{zx})}{\partial z} + \frac{\partial (v\tau_{xy})}{\partial x} + \frac{\partial (v\tau_{yy})}{\partial y}$$

$$+ \frac{\partial (v\tau_{yz})}{\partial z} + \frac{\partial (w\tau_{xz})}{\partial x} + \frac{\partial (w\tau_{yz})}{\partial y} + \frac{\partial (w\tau_{zz})}{\partial z}$$

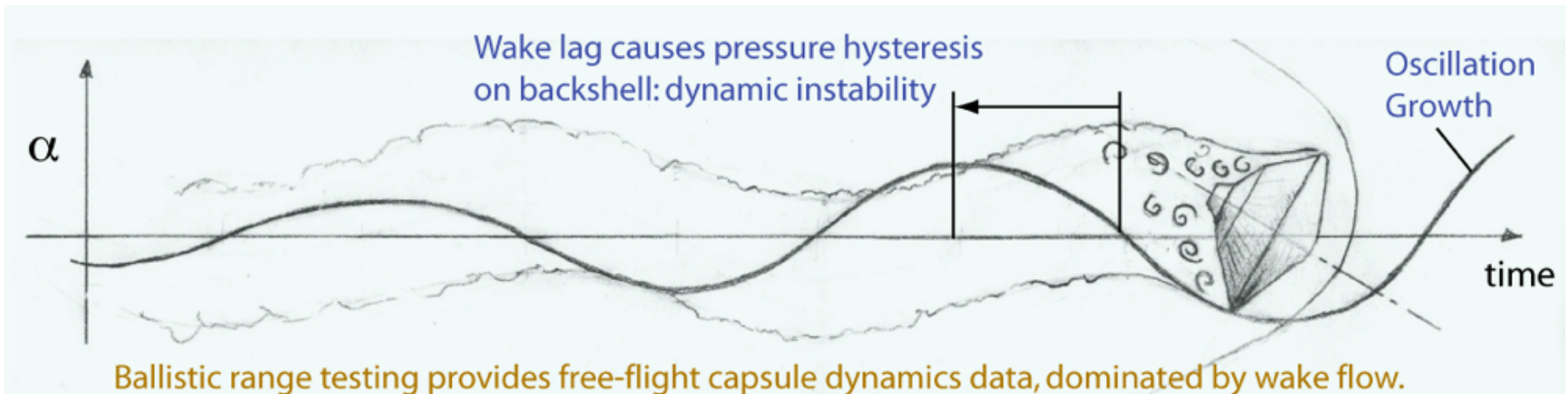
CFD Output



Dynamic Stability

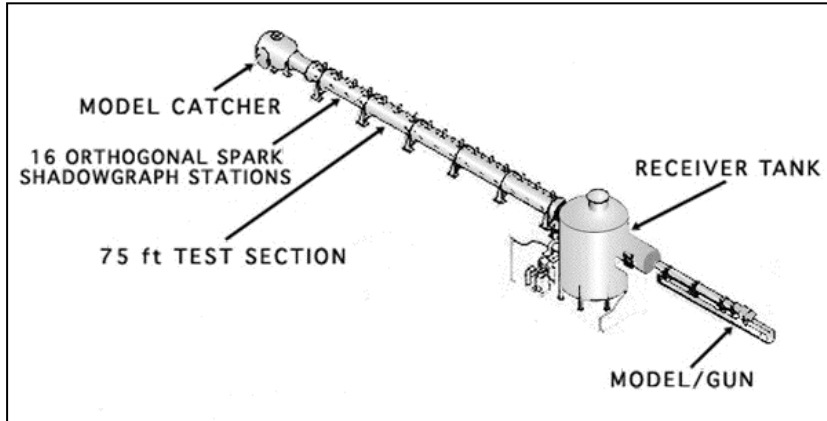


- Blunt bodies are dynamically unstable at supersonic speeds - driven by wake flow
- Phenomenon starts around Mach 3.5 and slower
- Stability can vary dramatically with backshell shape
- Unsteady CFD has provided insight on flow mechanisms
- Experiment is the only validated method of determining pitch damping coefficients

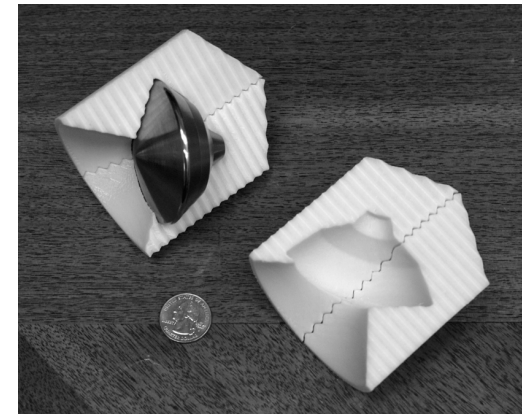
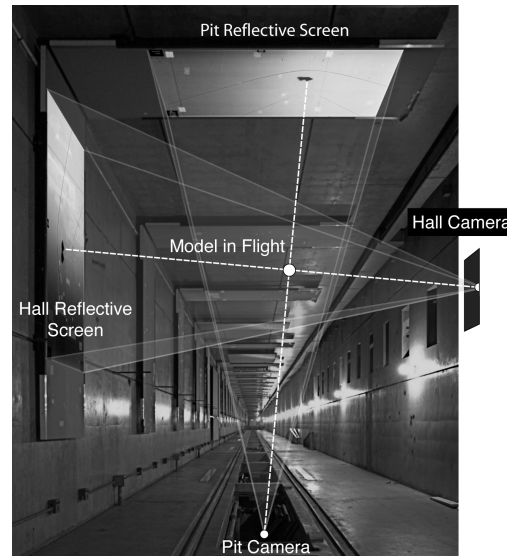
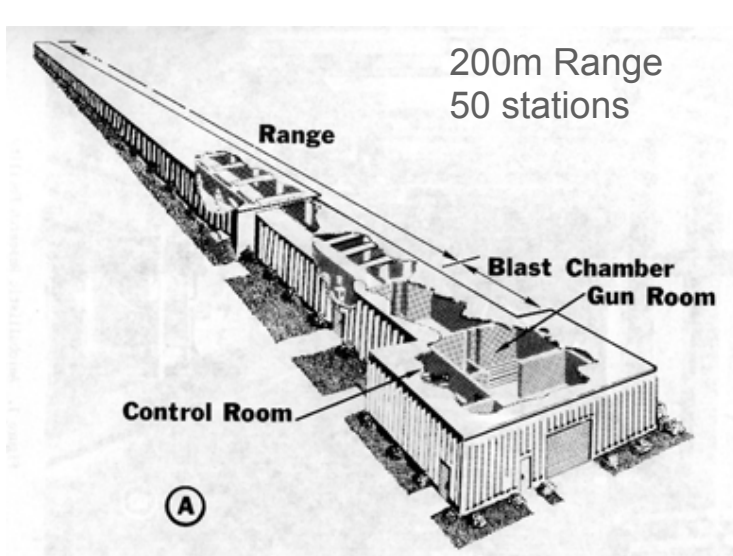


Free Flight Dynamic Stability Test Facilities

NASA Ames HFFAF (can test lifting, but Re is typically low)

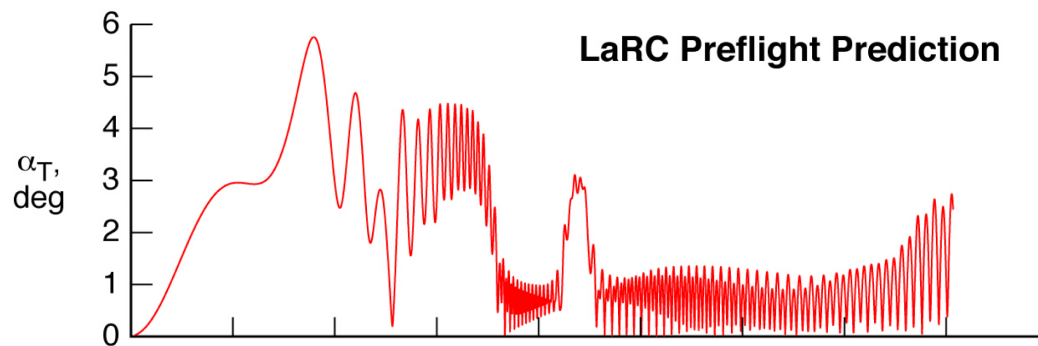


Eglin Air Force Base: Aeroballistic Test and Evaluation Facility (ATEF)
(Used for all recent robotic missions but currently mothballed)

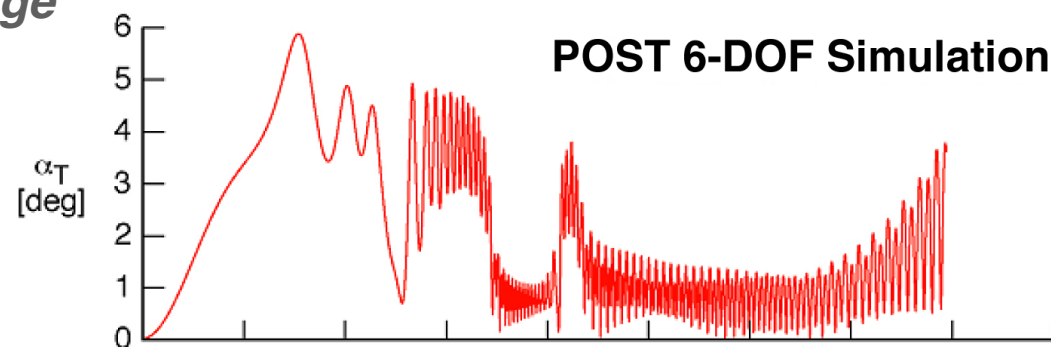


MSL model

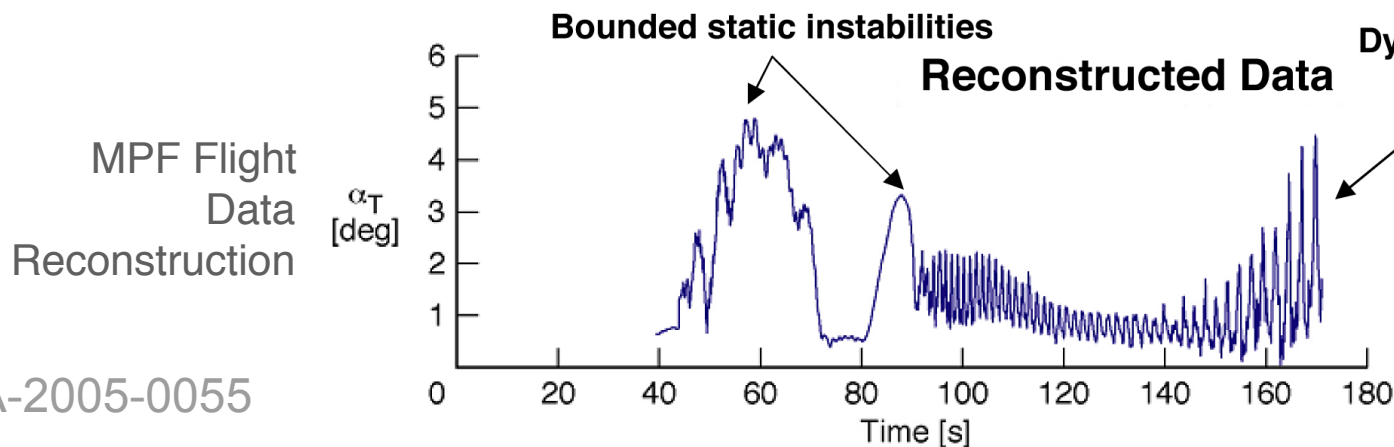
Mars Pathfinder Reconstruction



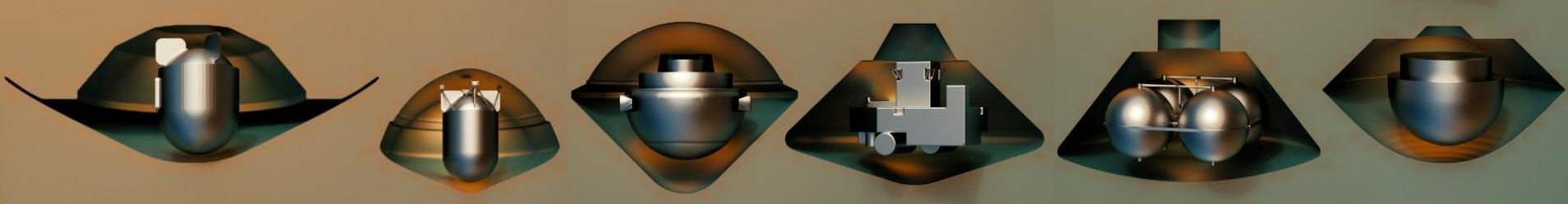
MPF
Preflight
Prediction



MER BR
Data in MPF
Prediction



[24] AIAA-2005-0055



Aerothermodynamics



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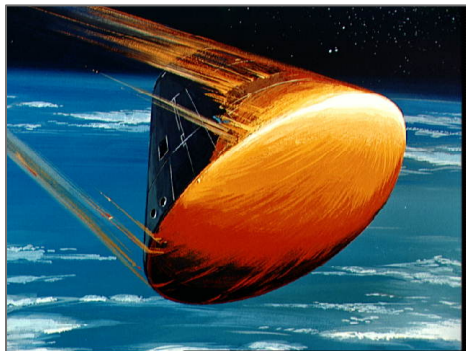


June 15-16, 2013

What is Aerothermodynamics?

- Definition: Aerodynamic heating of a solid surface by a gas through a viscous boundary layer & high-temperature shock layer
 - First addressed in the 1950s with the advent of hypersonic re-entry missiles
- Aerodynamic heating is most often associated with hypersonic atmospheric flight → high velocity + dense atmospheric gas = high temperatures

Apollo



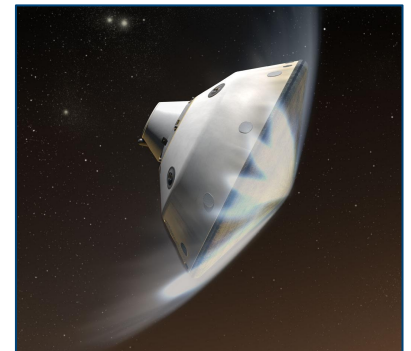
Space Shuttle



Pioneer Venus



Mars Science Laboratory

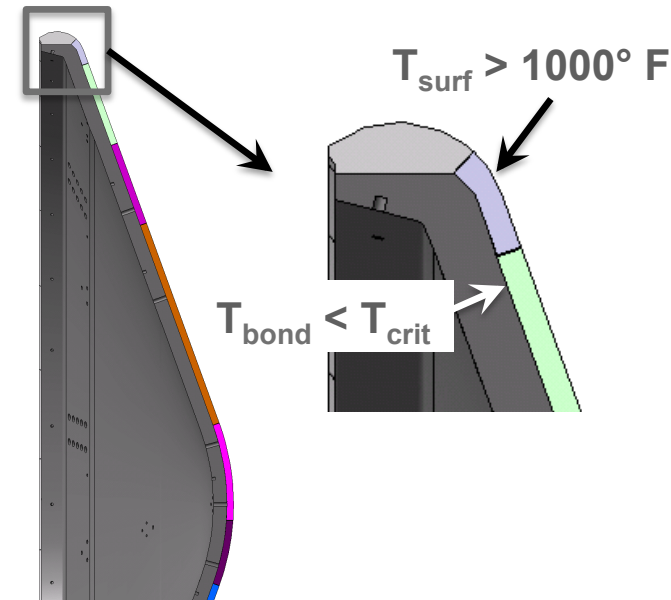
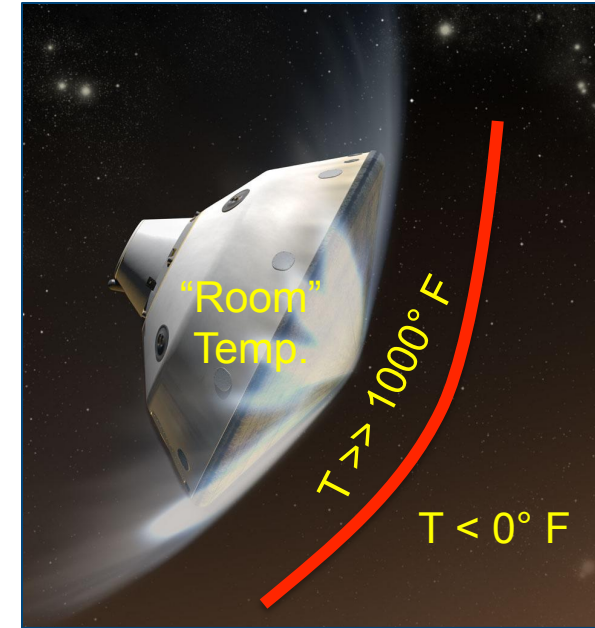


“Two major problems encountered today in aeronautics are the determination of skin friction and skin temperatures of high-speed aircraft.”

E. R. Van Driest, 1950

Thermal Protection

- Entry vehicle kinetic energy \rightarrow increased shock layer temperature \rightarrow increased surface temperature
- Payloads, human or robotic, must be protected from extreme temperatures
- Load-bearing structures cannot perform adequately at elevated temperatures
 - Material performance degrades
- The type & amount of thermal protection system (TPS) material depend on the prediction of aerodynamic heating at flight conditions
 - Heating = $f(\text{time})$, surface pressure & shear stress may also be important
 - Difficult/impossible to simulate flight conditions in ground facilities
- TPS adds mass to the EDL system!



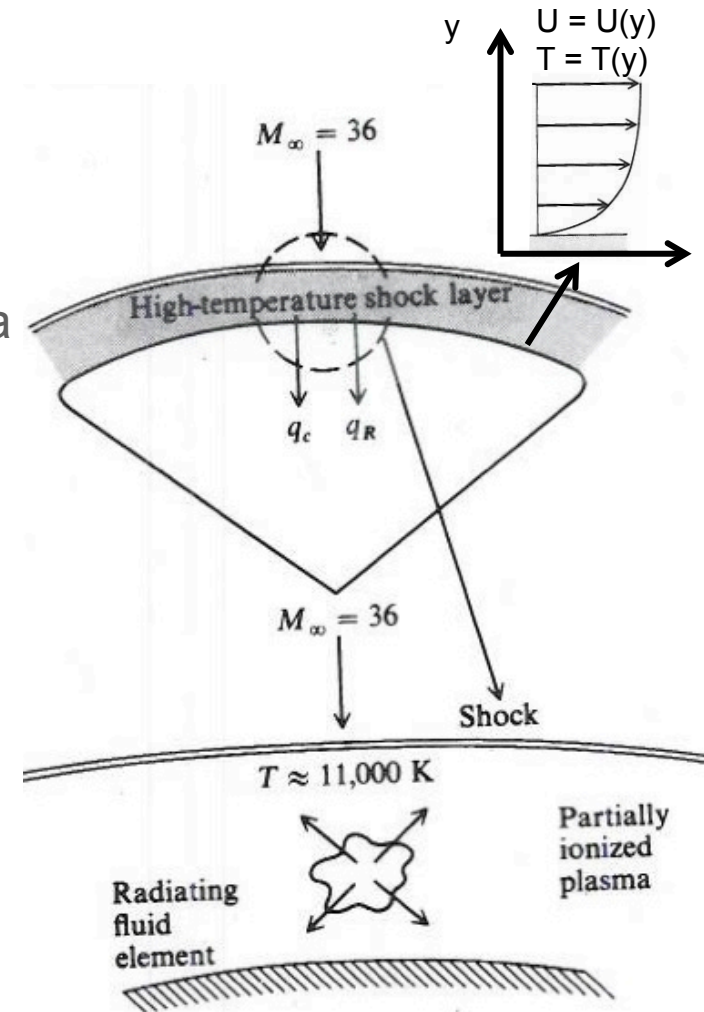
Terminology

- Convection = heat transfer via conduction & diffusion through a viscous boundary layer
 - Conduction ~ Temperature gradient at surface
 - Diffusion (aka Catalytic Heating) ~ Gas/surface chemical reactions
- Radiation = heat transfer via atomic excitation in a high-temperature shock layer
 - Radiation ~ Shock layer temperature

Convection Radiation

$$q_w = q_{Cond} + q_{Diff} + q_{Rad}$$

- Heat rate (q_w) = instantaneous heat transfer (W/cm^2)
- Heat load ($Q_w = \int q_w dt$) = integration of q_w (J/cm^2)
- Convective & radiative heating magnitudes depend on the entry vehicle & conditions
 - Mars: mostly convective
 - Earth (lunar return), Venus, Jupiter: convective & radiative

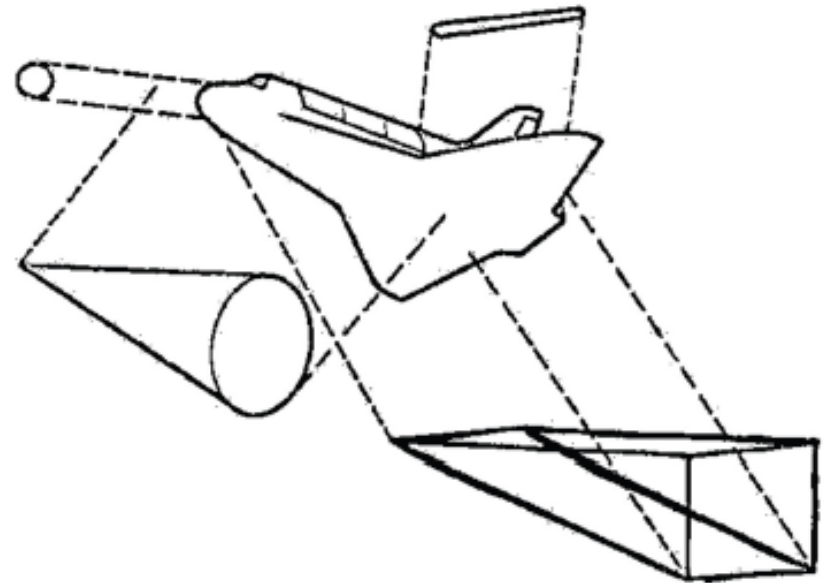


Schematic of Aerodynamic Heating to a Blunt Body (Ref. Anderson)

Engineering Methods

- Definition: Analytical solutions to the boundary layer equations
- Entry vehicles can be approximated by simple geometries
 - Nose (hemisphere), leading edge (cylinder), surface (cylinder or flat plate)
- Engineering methods have an important place in conceptual vehicle design
 - Quick to use, based on theory, can be integrated into trajectory codes
- Examples for stagnation point heating:
 - Requires effective nose radius (R_n)

Simplified Entry Vehicle Geometries



Fay & Riddell (1958)
$$\dot{q}_w = \frac{0.763}{(\text{Pr}_w)^{0.6}} (\rho_e u_e)^{0.4} (\rho_w u_w)^{0.1} [(h_o)_e - h_w] \left[1 + (Le^{0.52} - 1) \frac{h_d}{(h_o)_e} \right] \left[\left(\frac{du_e}{dx} \right)_t \right]^{0.5}$$

Sutton & Graves
(Convective)
$$q_c = C \left(\frac{\rho_\infty}{R_n} \right)^{\frac{1}{2}} V_\infty^3$$

Earth: $C = 1.7415\text{e-}4$

Mars: $C = 1.9027\text{e-}4$

\downarrow
 $\sim 1/R_n$

Tauber & Sutton
(Radiative)
$$q_r = C_i R_n^a \rho_\infty^m f_i(V_\infty)$$

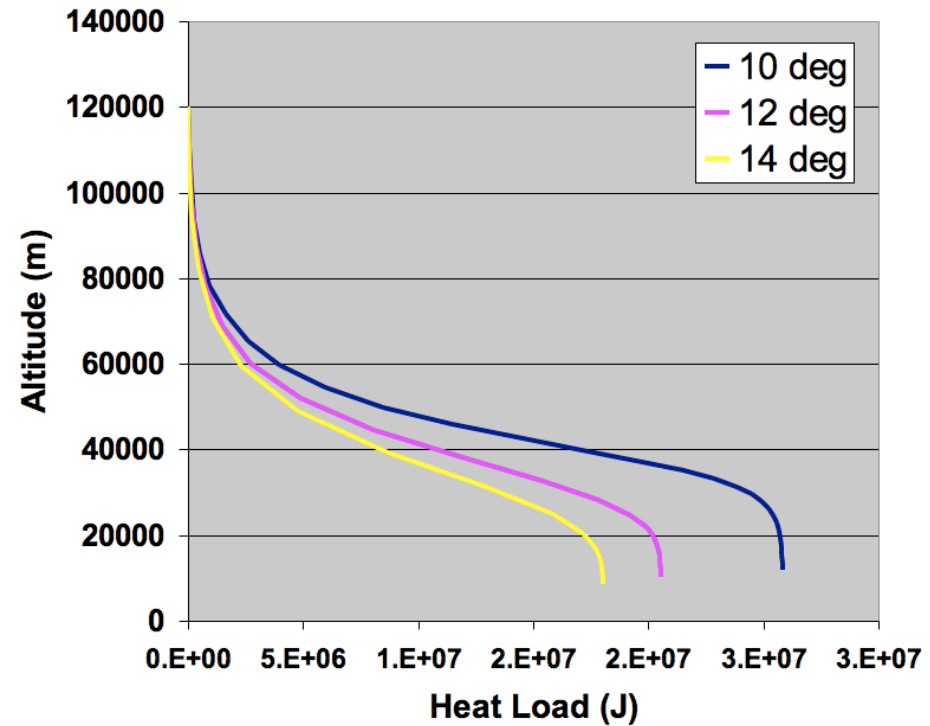
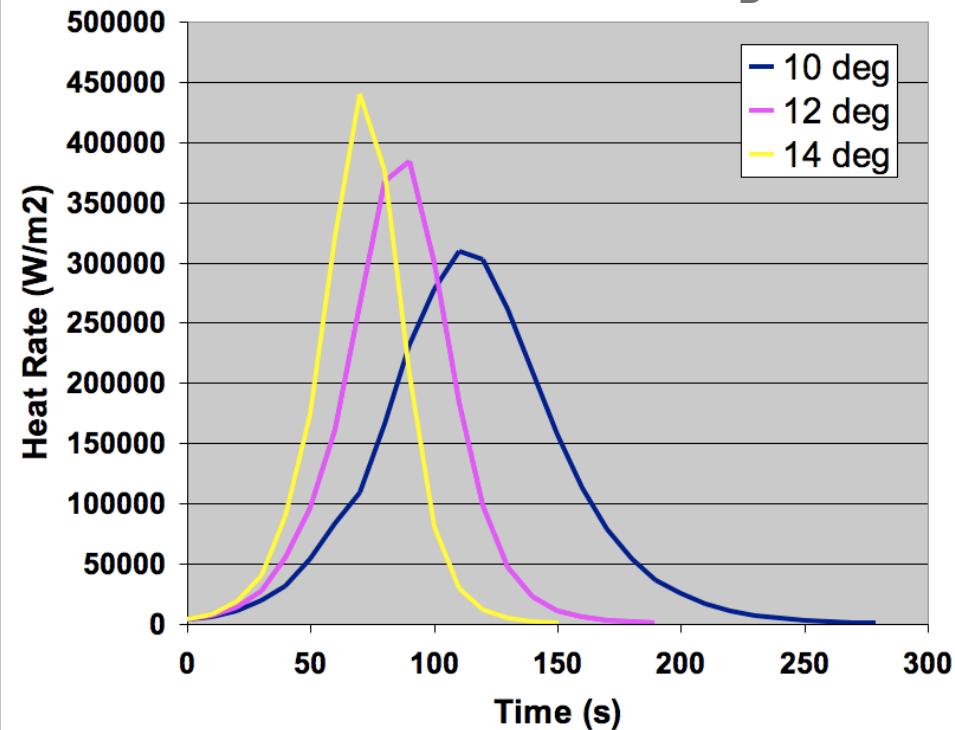
Earth: $a = 1, m = 1.2$

Mars: $a = 0.526, m = 1.2$

Example: Mars, Effect of Flight Path Angle

- Assumptions: Sutton-Graves stagnation point heating ($R_n = R_{eff}$), ballistic entry, exponential atmospheric density
- A steeper FPA increases max. heat flux, but decreases heat load (TPS thickness)
 - Potential for TPS mass savings by using a steeper entry

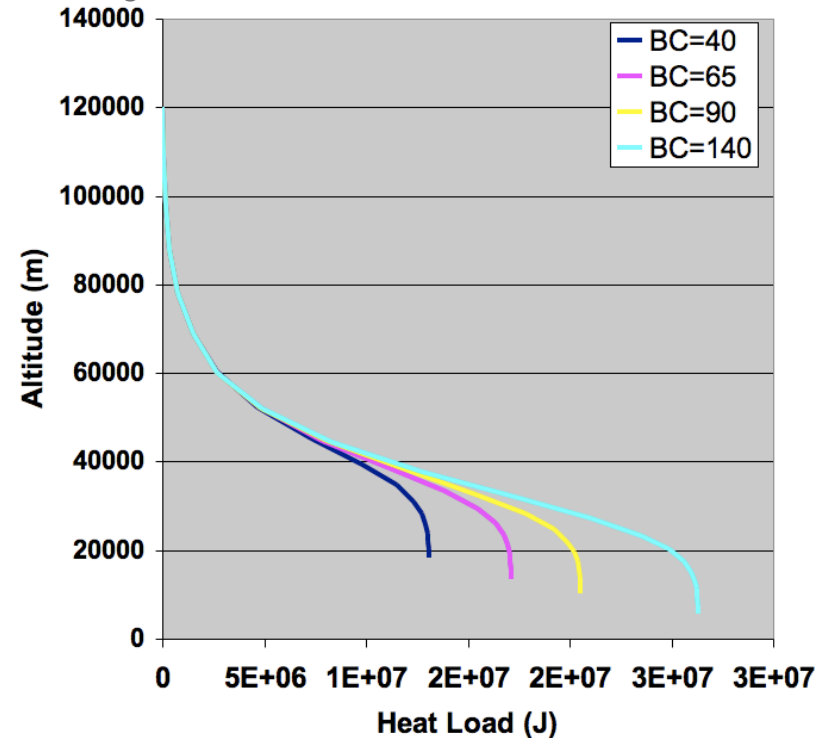
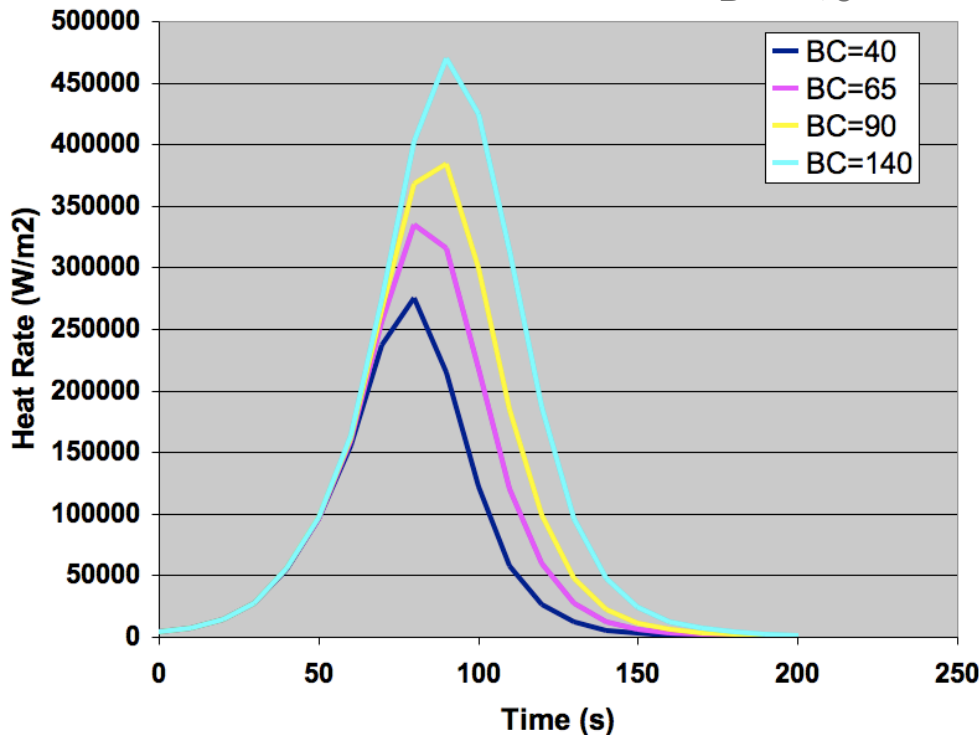
$$BC = m/C_D A = 90 \text{ kg/m}^2; V_e = 5.5 \text{ km/s}$$



Example: Mars, Effect of Ballistic Coefficient

- Assumptions: Sutton-Graves stagnation point heating ($R_n = R_{\text{eff}}$), ballistic entry, exponential atmospheric density
- If the BC increases, heating will increase
 - Example: payload mass grows, but aeroshell diameter does not

$BC = m/C_D A$, $\gamma_e = -12$ deg, $V_e = 5.5$ km/s

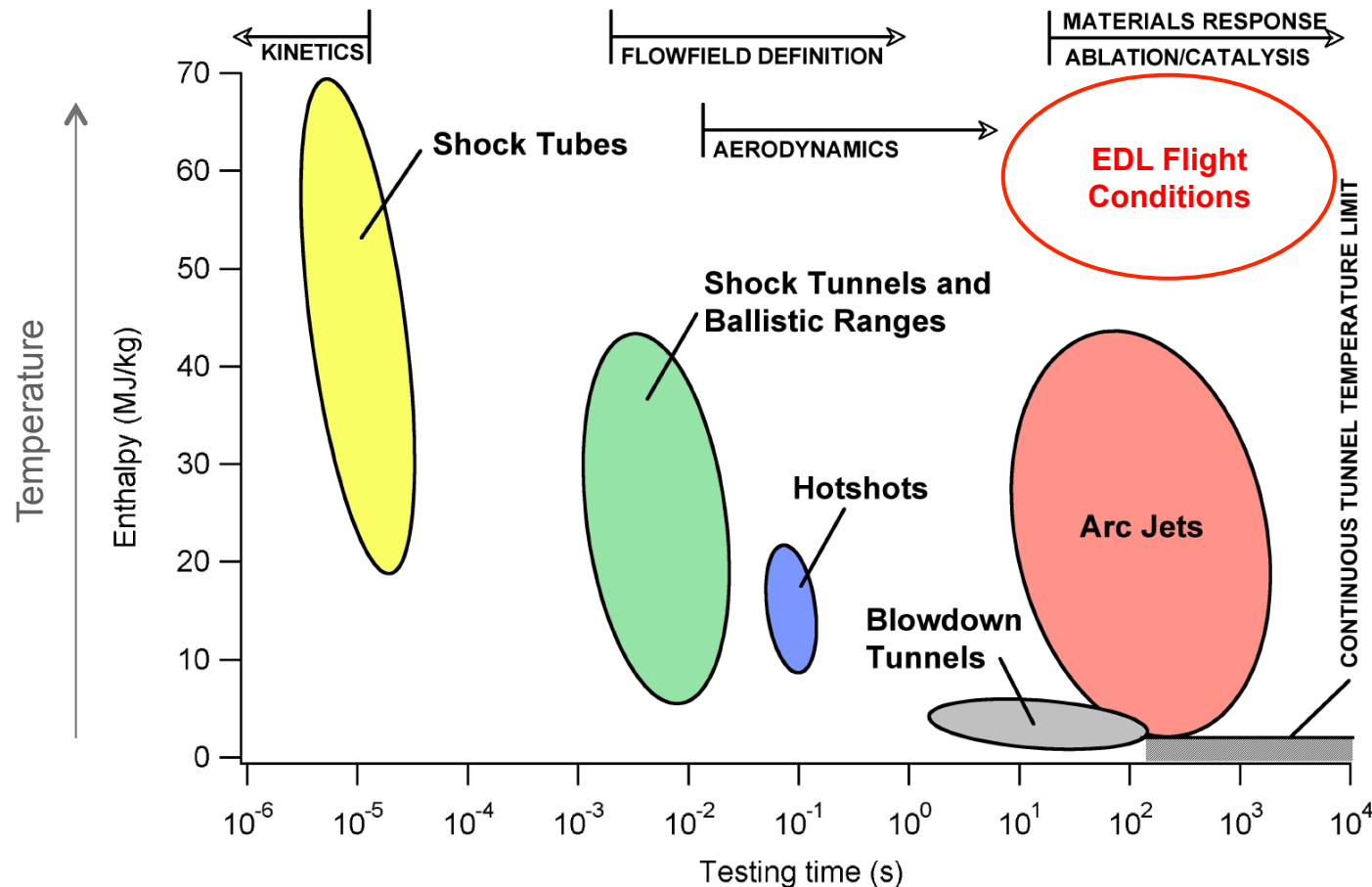


Rules of Thumb for Ballistic Entry

- Stagnation point convective heating: $q_c \sim \rho_\infty^{1/2} V_\infty^3 / R_n^{1/2}$
- Stagnation point radiative heating: $q_r \sim R_n^m$
- Wall temperature: $T_w^4 \sim q_c$
- Convective heat flux, q_c :
 - ↑ with ↑ entry velocity
 - ↑ with ↑ ballistic coefficient (mass)
 - ↑ with ↑ entry flight path angle
- Convective heat load: $Q_c = \int q_c dt$
 - ↑ with ↑ entry velocity
 - ↑ with ↑ ballistic coefficient (mass)
 - ↑ with ↓ entry flight path angle

Ground-to-Flight Traceability

- Ground-based testing, while valuable, cannot replicate all EDL flight conditions
 - Technically & fiscally prohibitive to build & run such facilities
- Aerodynamic heating analysis at flight conditions is usually left to engineering methods (conceptual) & high-fidelity CFD models (TPS design)
 - Ground data are used to anchor models to be used for flight predictions

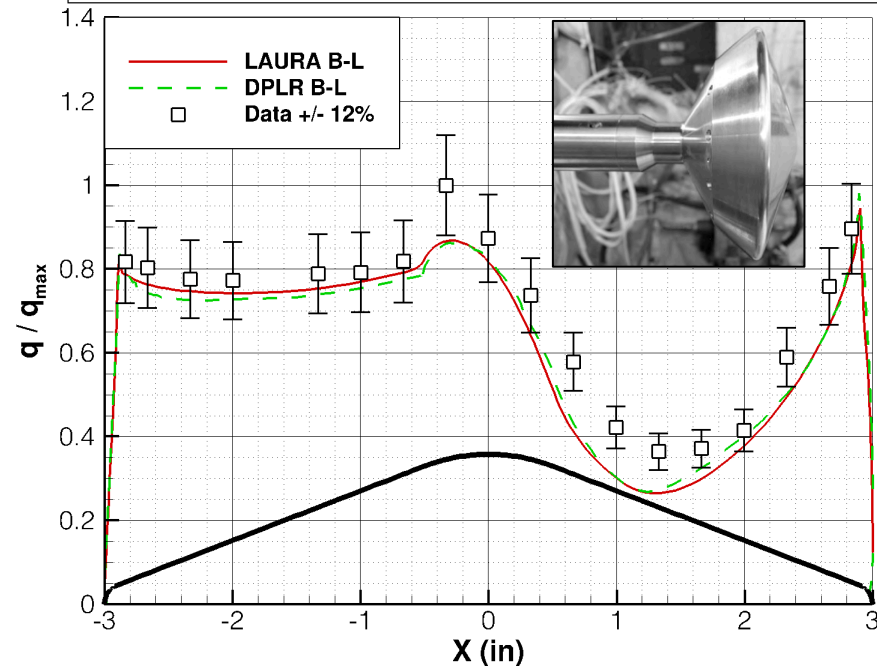


Ground-to-Flight Traceability

- Heating magnitudes in ground facilities \neq heating in flight
 - Differences in Mach, Re, gas composition...
- Ground facilities are used to understand qualitative heating and to provide a source of data for CFD validation
 - Ground testing does not generally include TPS response, which is added post-CFD

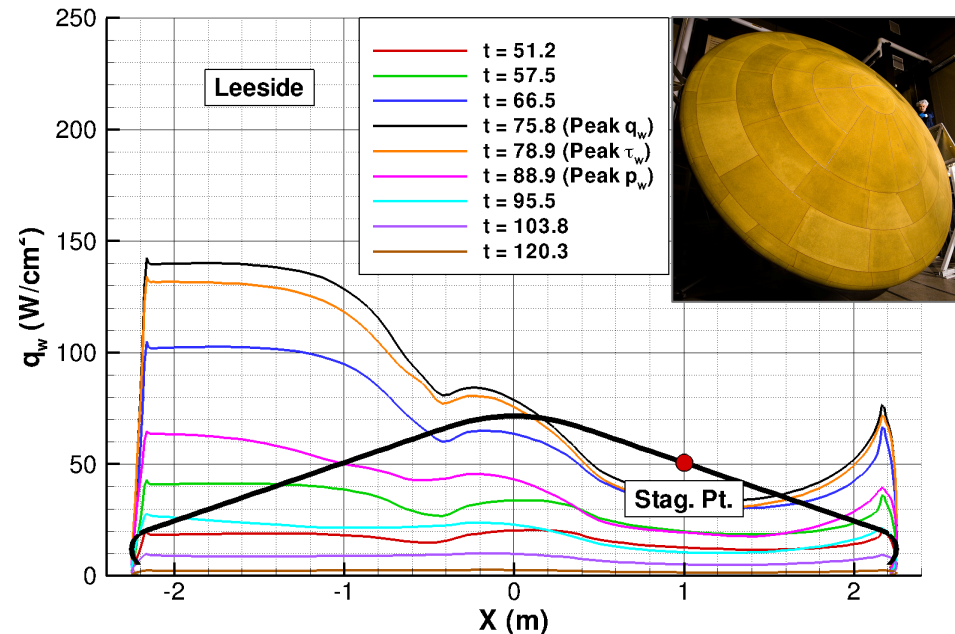
MSL Testing in AEDC Tunnel 9 (Mach 8)

AEDC T9 Run 3048 (Mach = 8, $Re_{\infty,D} = 24.8 \times 10^6$, $\alpha = 16$ deg)



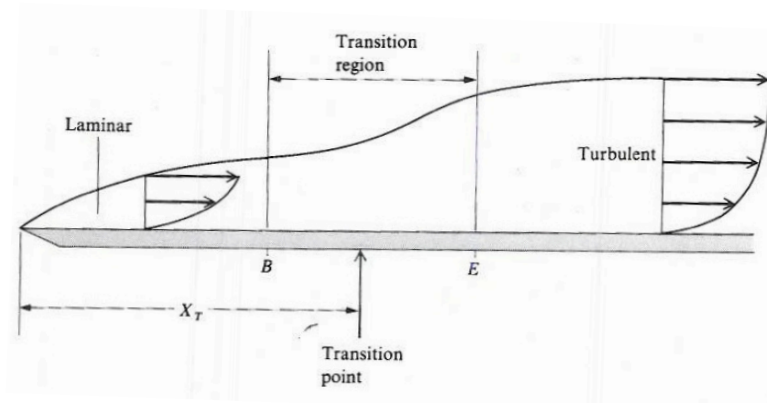
MSL Flight CFD (30 > Mach > 7)

09-TPS-02 Nominal Trajectory (LAURA B-L Solutions, Baseline)

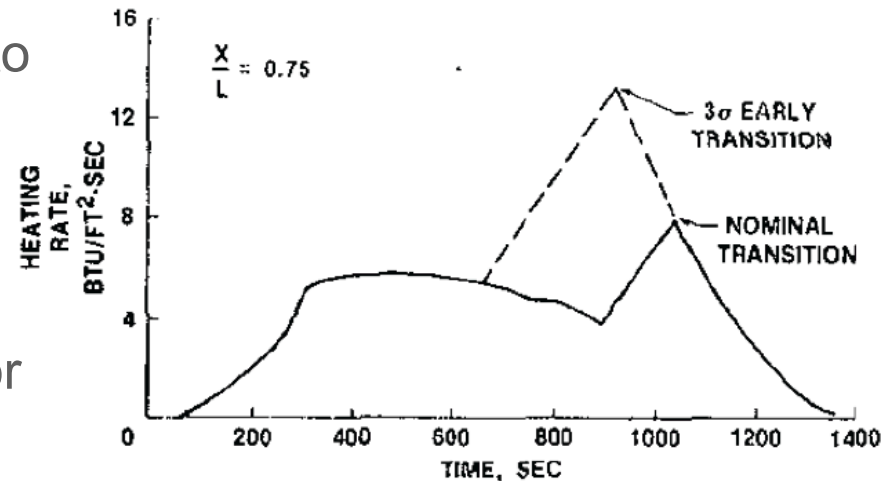


Boundary Layer Transition (BLT)

- Predicting BLT is one of the most difficult aspects of aerodynamic heating
 - Mechanisms not well understood
- BLT can increase max. heat flux and total heat load → TPS mass & performance
 - $q_{\text{Turb}} > \text{or } \gg q_{\text{Lam}}$
 - Stagnation point may not have highest q_w
- Engineering methods are often used to predict BLT timing
 - BL momentum-thickness Reynolds no., $Re_\theta > Re_{\theta, \text{crit}}$
 - Examples: Space Shuttle, MSL
- Conservative approach is to design for turbulent conditions using CFD



Schematic of BLT (Ref. Anderson)

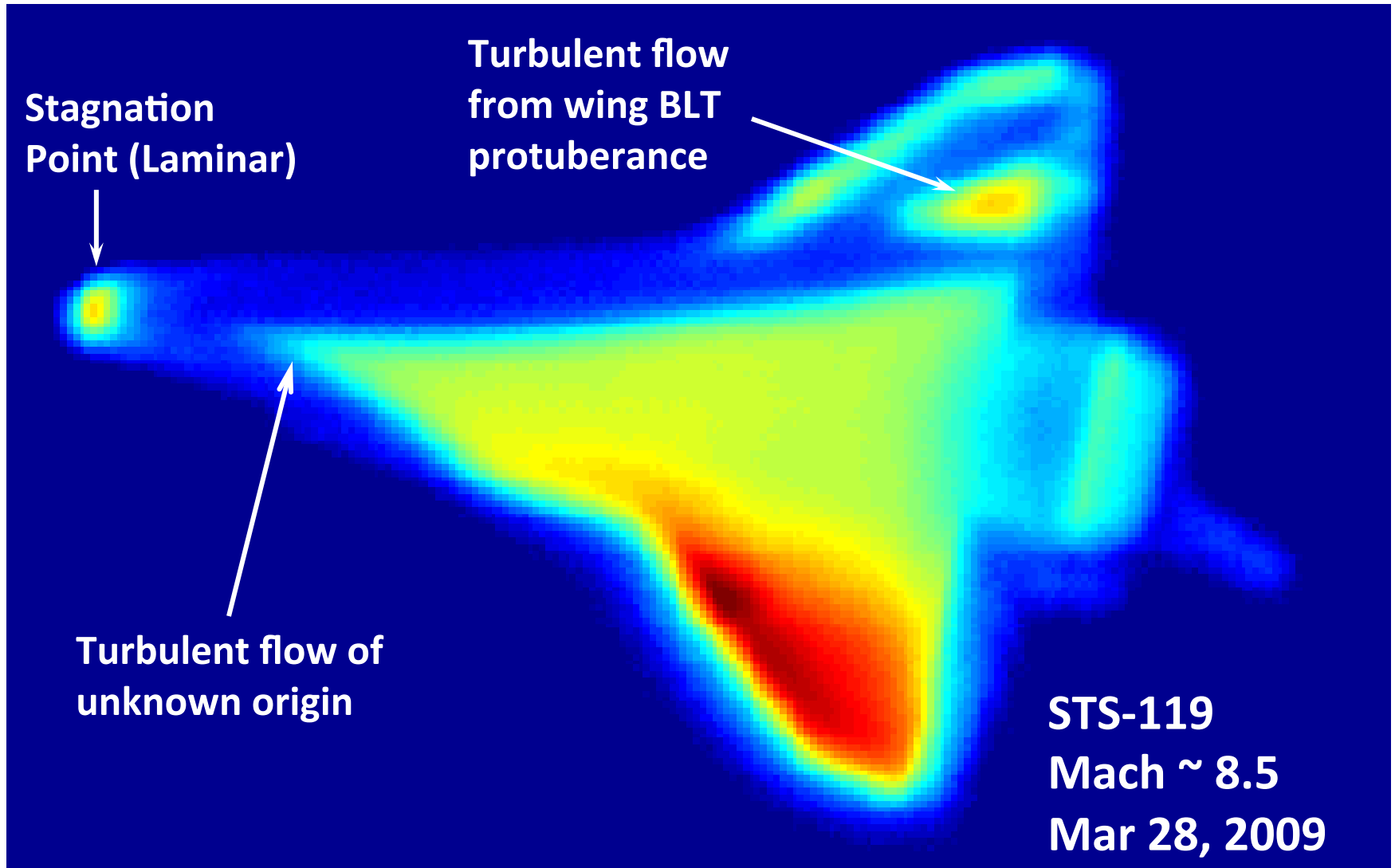


**BLT Design for Space Shuttle
Windward Body Point
(Ref. AIAA 79-1042)**

"When I meet God, I am going to ask him two questions: Why relativity? And why turbulence? I really believe he will have an answer for the first." - Werner Heisenberg

BLT on STS-119

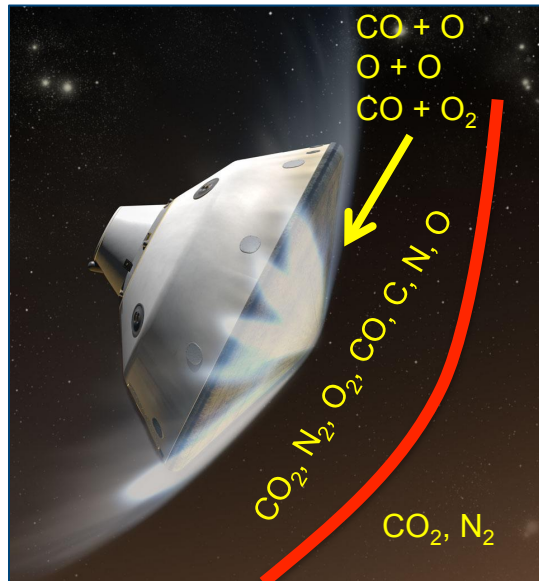
- HYTHIRM imagery of Space Shuttle lower surface



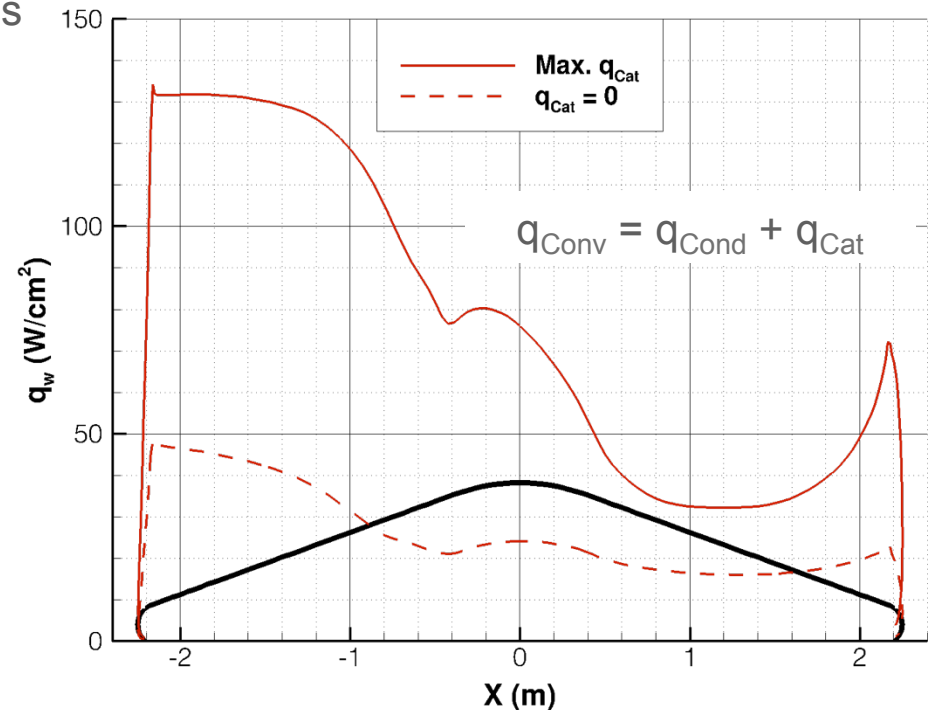
Catalytic Heating

- High shock-layer temperature dissociates gas molecules
 - Mars: CO_2/N_2 in front of shock \rightarrow CO_2 , N_2 , O_2 , CO , C , N , O behind shock
 - Earth: N_2/O_2 in front of shock \rightarrow N_2 , O_2 , N , O , NO + ions behind shock
- Post-shock gas may recombine at surface
 - Heat of reaction = Catalytic heating = Higher convective heating
- Conservative approach is to maximize catalytic heating
 - “Super-catalytic” = recombine all atoms

Mars Non-Equilibrium Chemistry



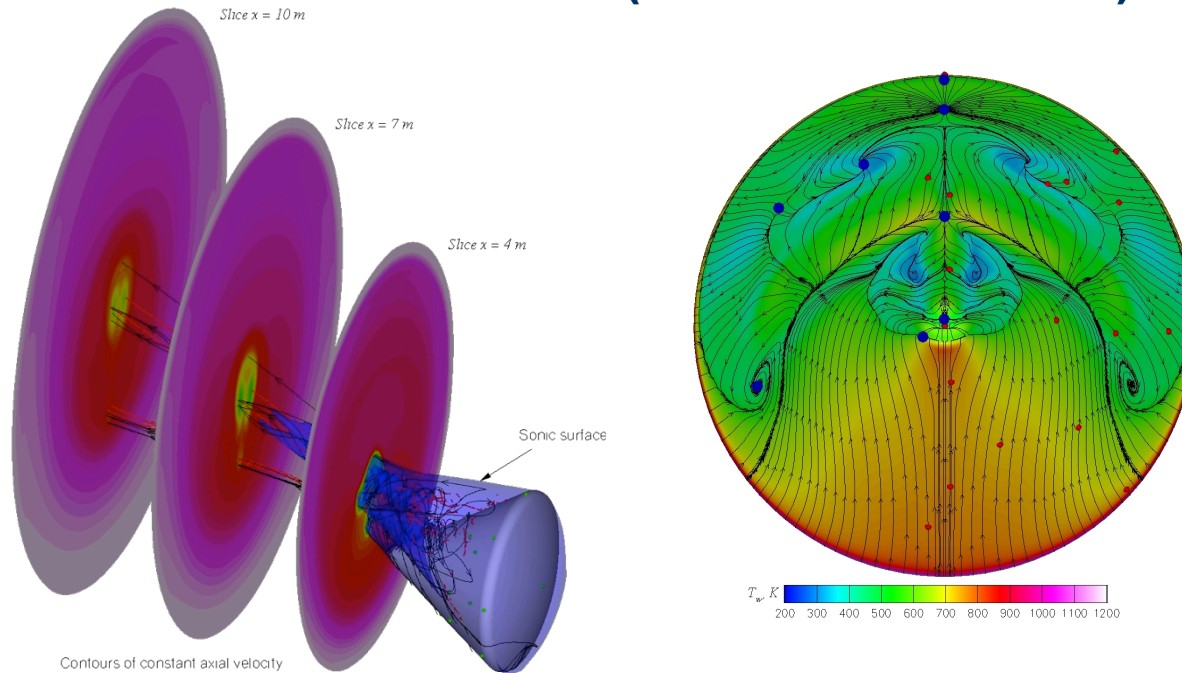
MSL Predicted Convective Heat Flux at Peak Heating (No Uncertainties)



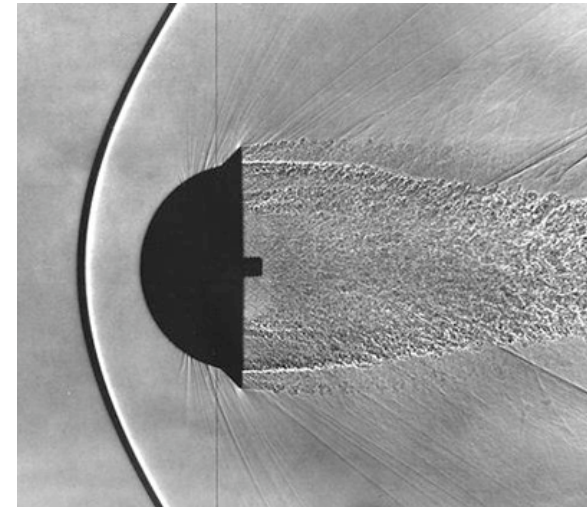
Aftbody Heating

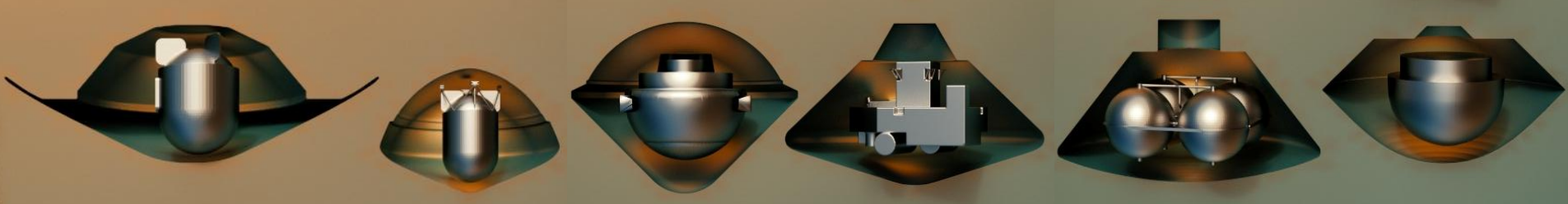
- Heating on vehicle components that are in the wake of a hypersonic flowfield are more difficult to predict
 - Separated, unsteady, turbulent, low-density flow
 - Uncertainties are > than for heatshield
- Heating is generally < 10% of stagnation point heating for a blunt body

DPLR CFD of AS-202 (Ref. AIAA 2004-2456)



Ballistic Range Model





Case Study: Mars Science Laboratory



International Planetary Probe Workshop 10, EDL Short Course

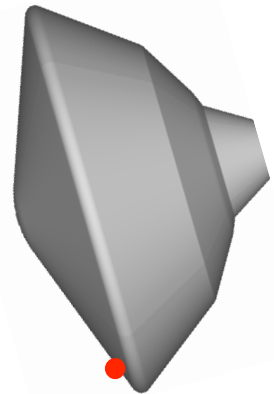
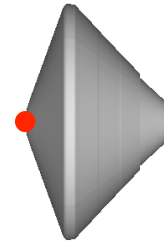
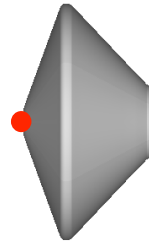
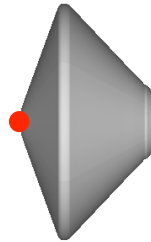
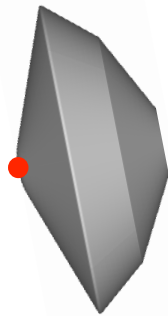


June 15-16, 2013

Mars Science Laboratory (MSL)

- Guided entry (trim $\alpha = -16$ deg, trim $L/D = 0.24$), RCS bank control
- Large heatshield + high $m/C_D A = \text{BLT}$ expected prior to peak heating, resulting in high heating rate

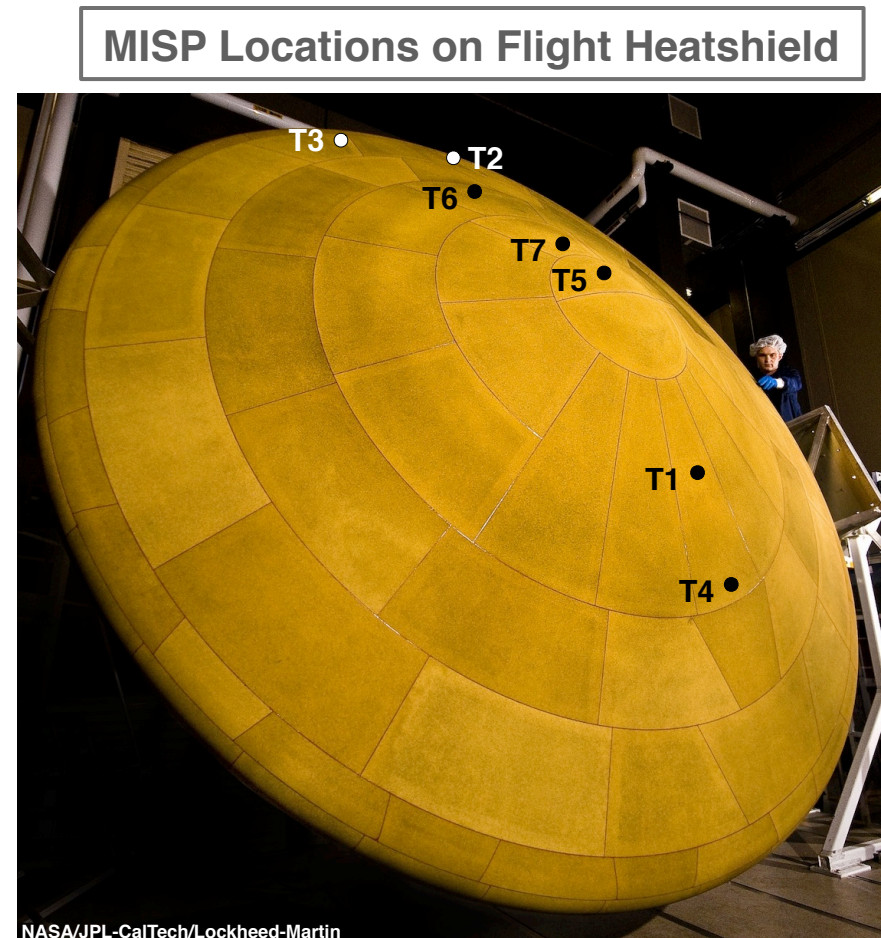
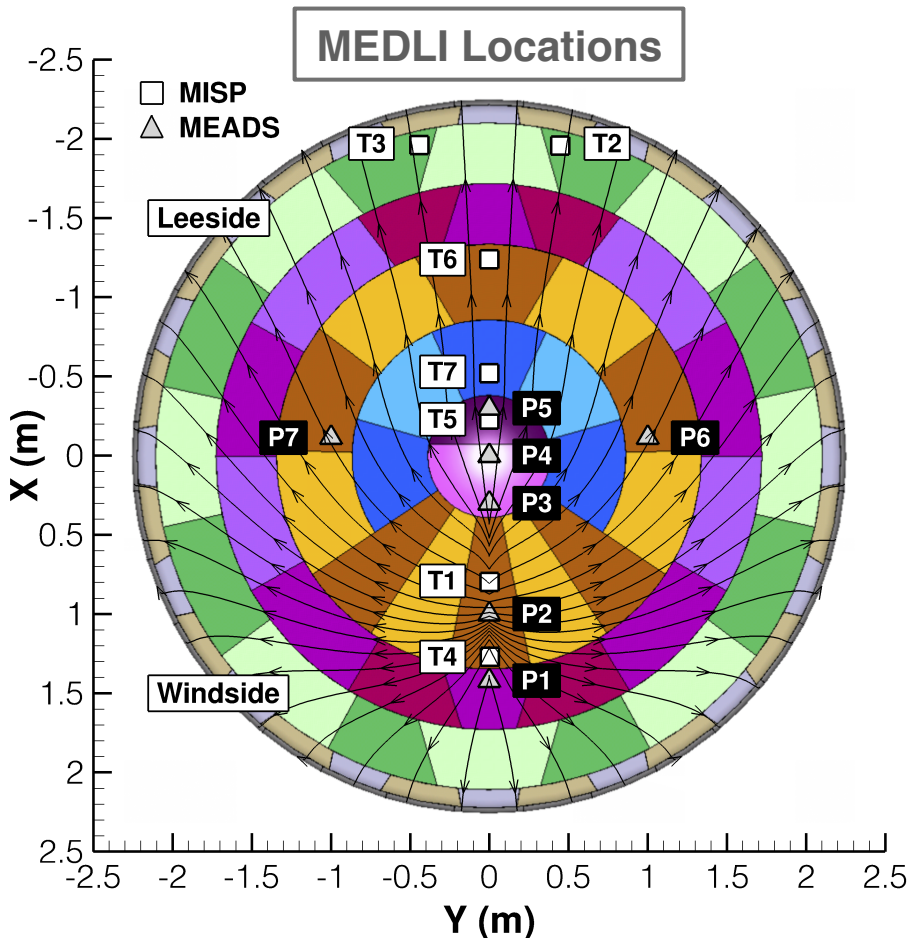
Viking 1/2 Pathfinder MER A/B Phoenix MSL



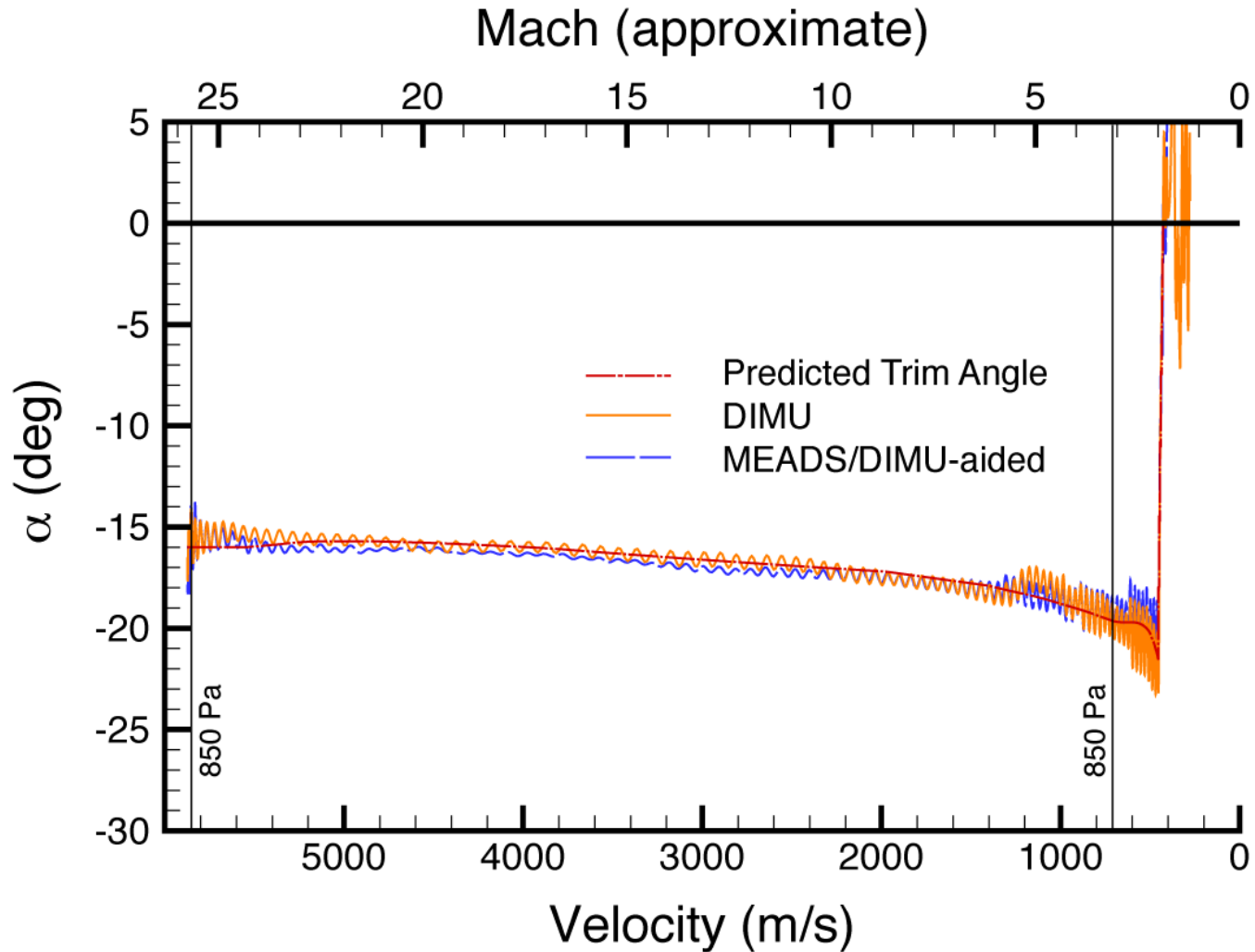
Diameter, m	3.5	2.65	2.65	2.65	4.5
Entry Mass, kg	930	585	840	602	3152
Entry Vel., km/s	4.5/4.42	7.6	5.5	5.9	5.9
Entry FPA, deg	-17.6	-13.8	-11.5	-13	-16.1
$m/(C_D A)$, kg/m ²	64	62	90	65	135
Hypersonic α , deg	-11.2	0	0	0	-16
Hypersonic L/D	0.18	0	0	0	0.24
Heat Flux, W/cm ²	24	106	48	56	>200 (Design)

MSL Heatshield & MEDLI Instrumentation

- MISP: 2-4 thermocouples (0.1-0.7 in below surface) at 7 locations
 - Surface heating comes from inverse analysis of temperature data
- MEADS: pressure transducer at 7 separate locations → capsule attitude



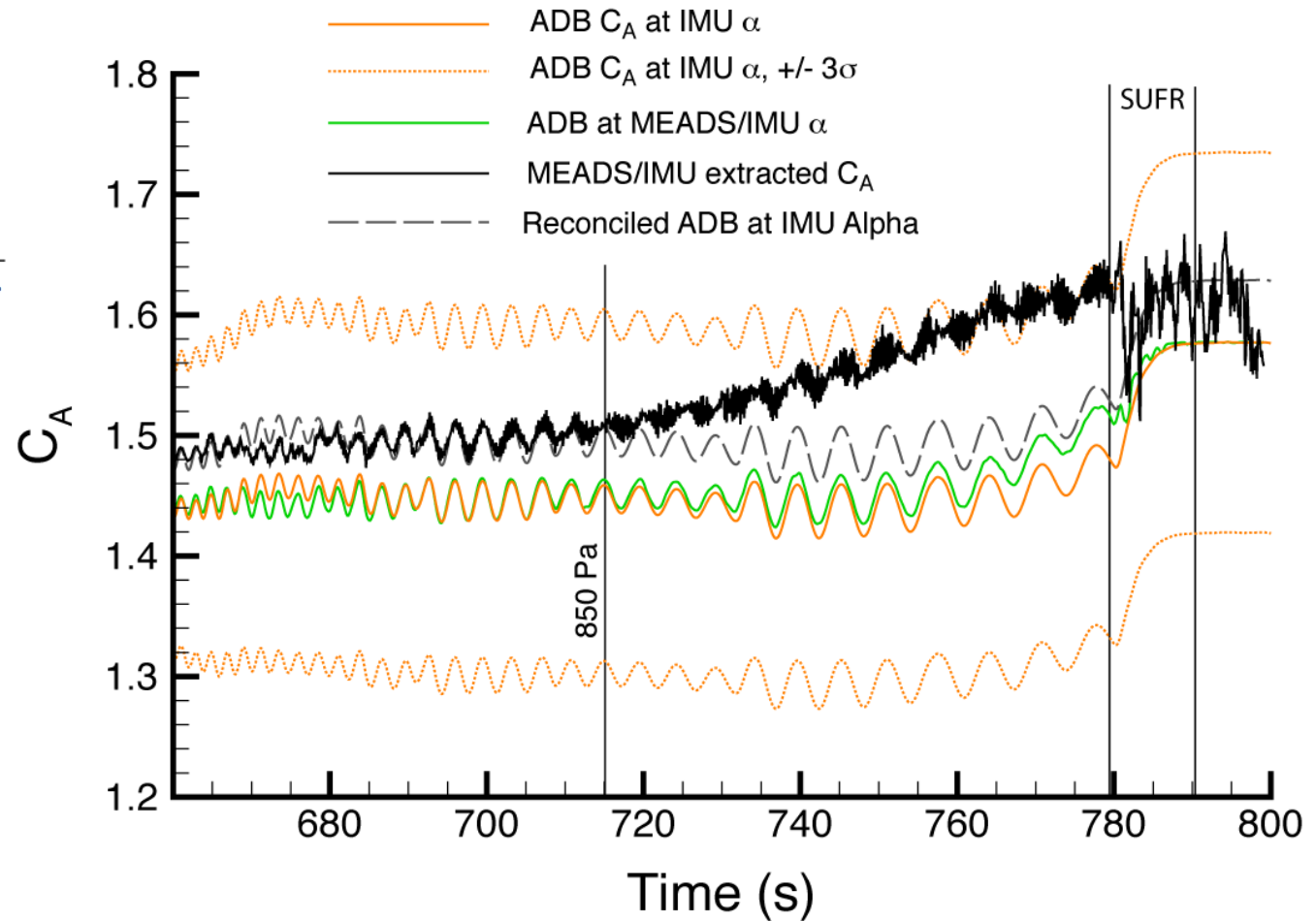
MSL Reconstructed Angle-of-Attack [28]



- Trim angle and Lift-to-Drag predictions were very accurate

MSL C_A [28]

$$C_A = - \frac{m_{EV} a_x}{q_{\infty, MEADS} S_{ref}}$$

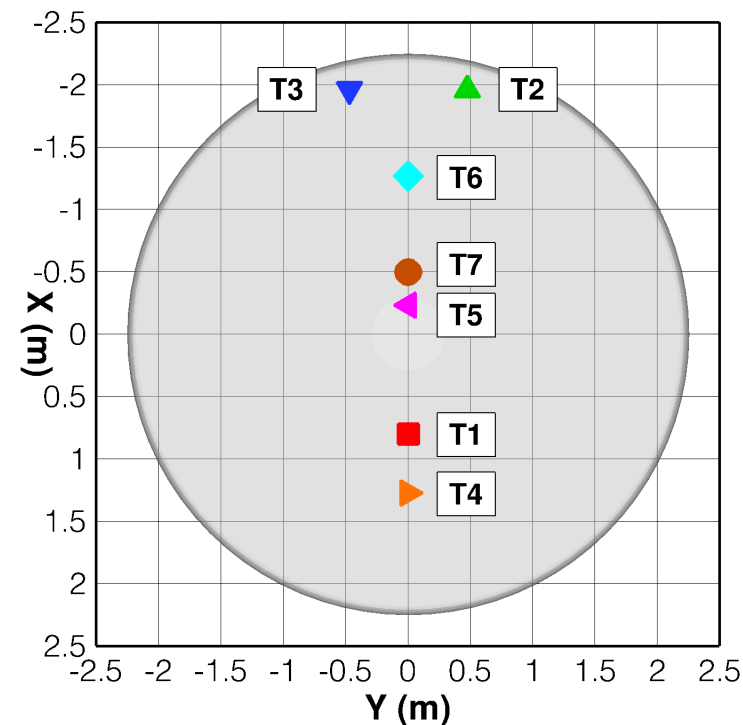
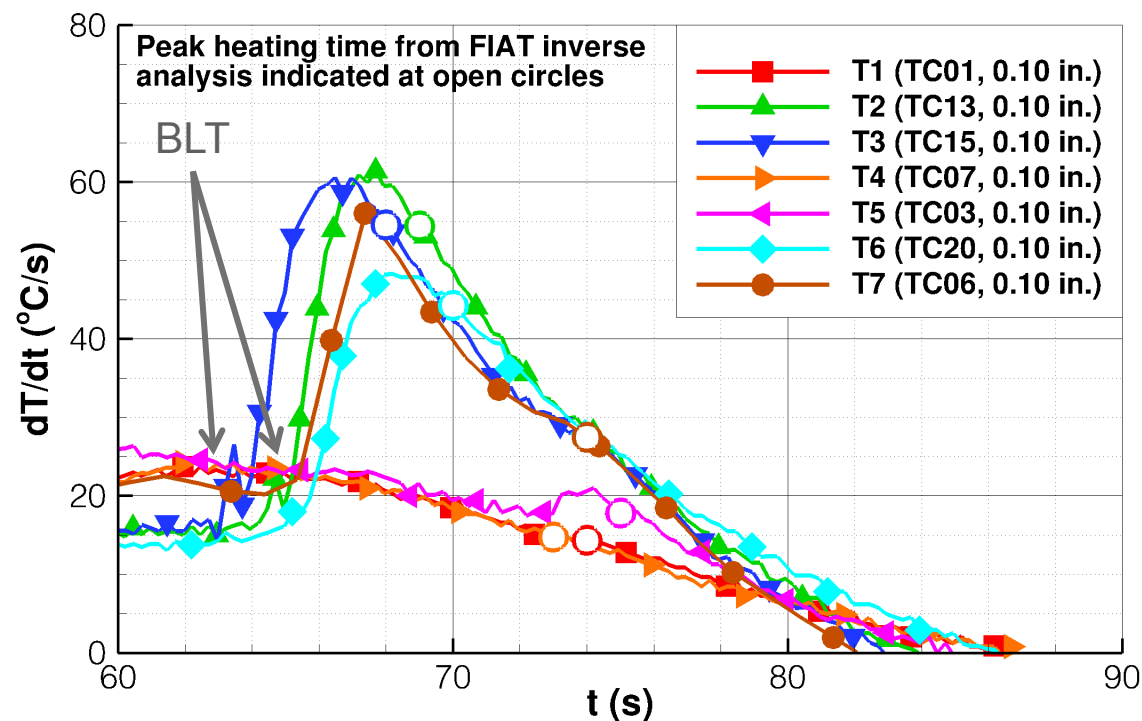


- MEADS Supersonic C_A remains area of study
- Viking-derived base pressure correction remains possible error source
- **Winds and supersonic drag are the two dominant contributors to landing miss distance**

MSL Boundary Layer Transition

- BLT indicated by rapid increase in dT/dt
- MISP T2, T3, T6, and T7 all experienced BLT
- Small bump at T5 believed to indicate BLT
- All BLT events occurred prior to peak heating, as expected

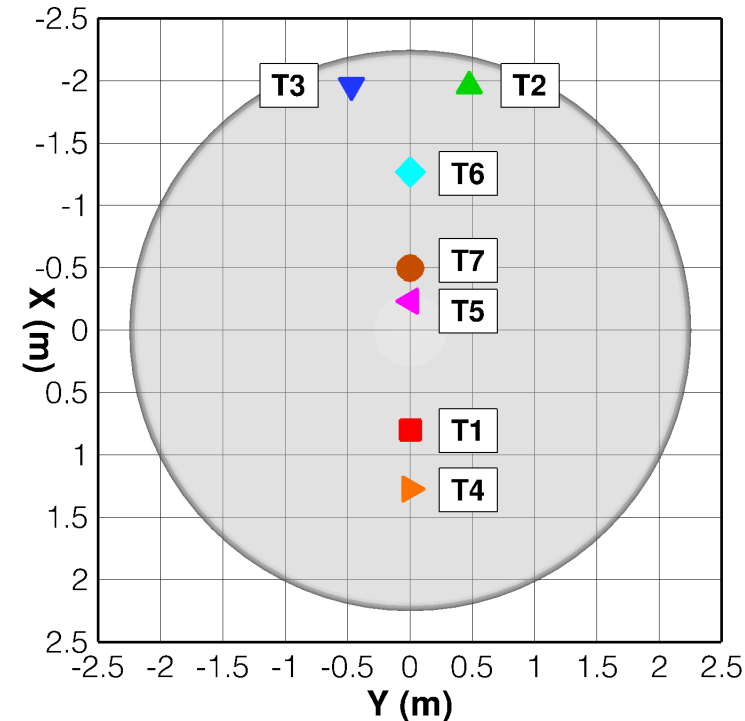
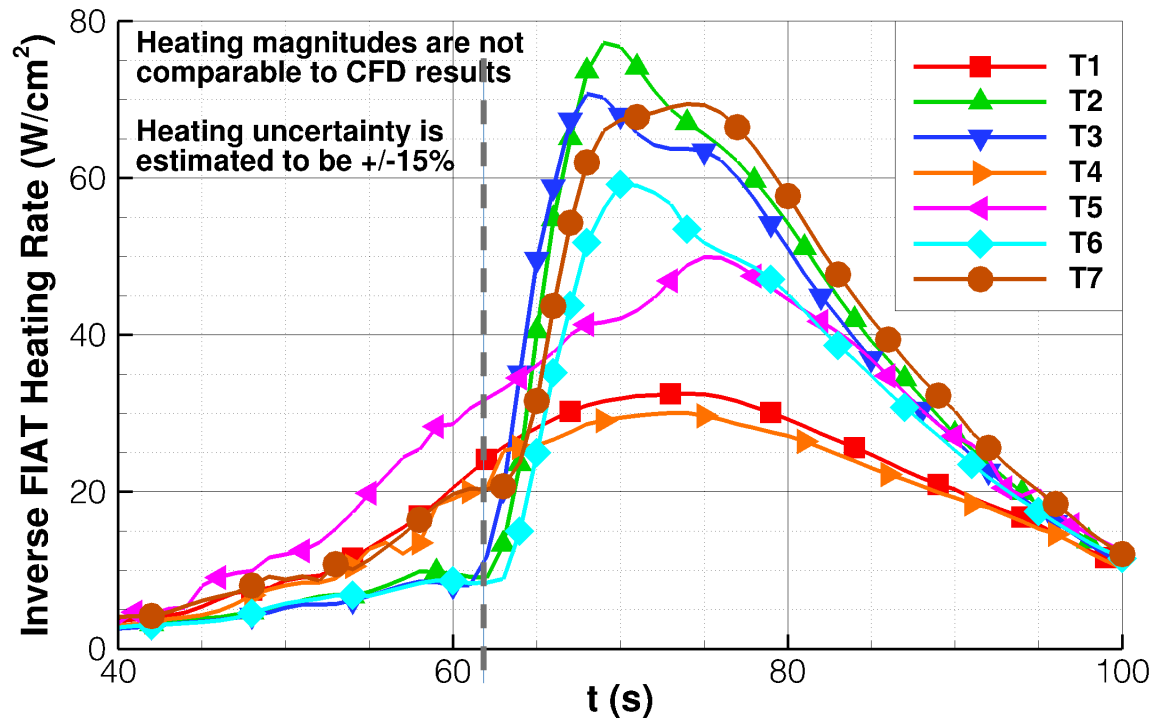
Time Rate-of-Change of Temperature 0.1 in. Below Surface



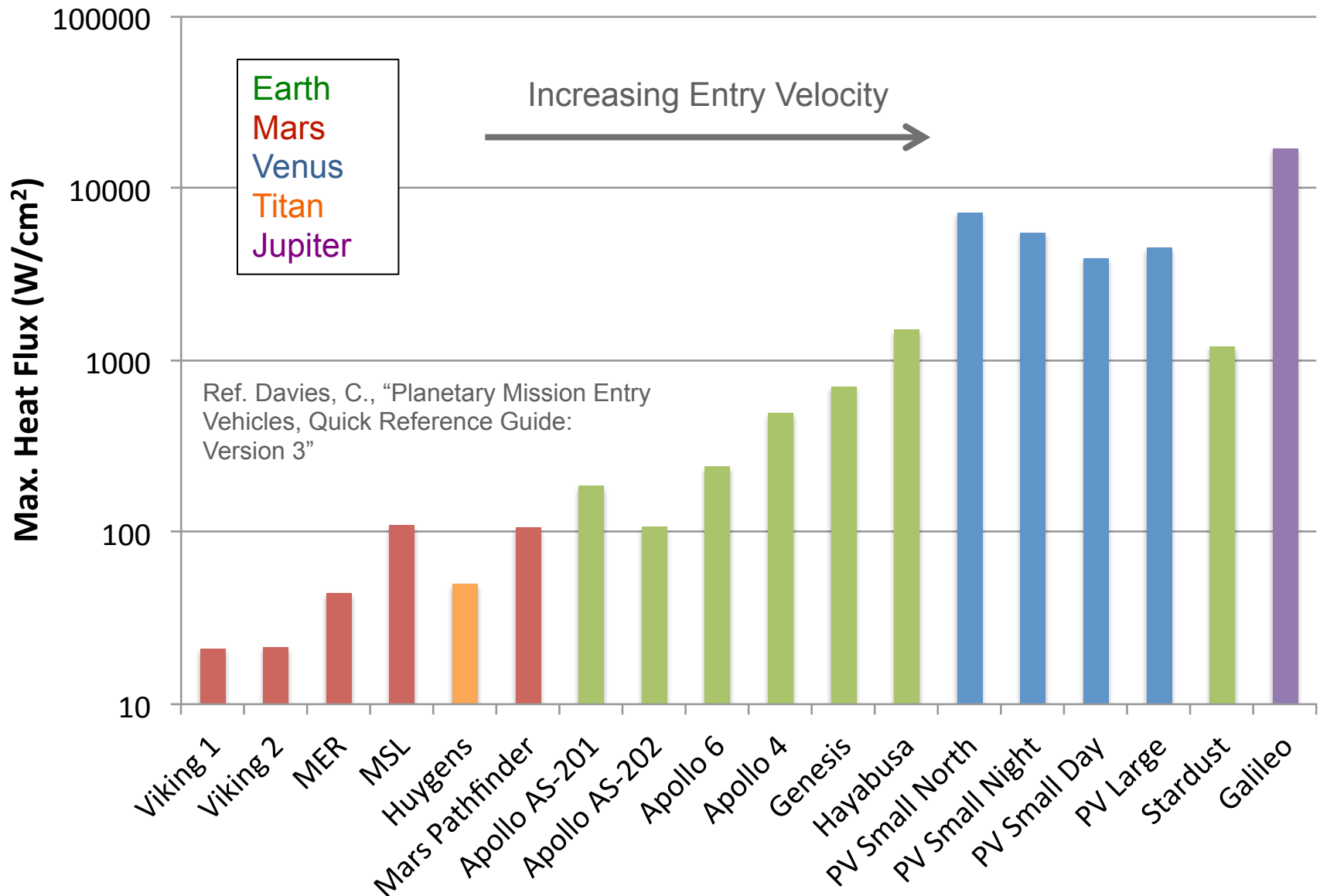
MSL Reconstructed Heating

- Expected results:
 - Laminar heating highest at T5
 - Laminar heating lowest at T2, T3, T6
 - Turbulent heating highest at T2, T3
- Unexpected results:
 - High turbulent heating at T7 relative to T2, T3 \rightarrow roughness?
 - High heating at T1, T4 relative to T2, T3 \rightarrow radiation?

MISP Heating Rate from FIAT Inverse Analysis (Estimated $\pm 15\%$ Uncertainty)

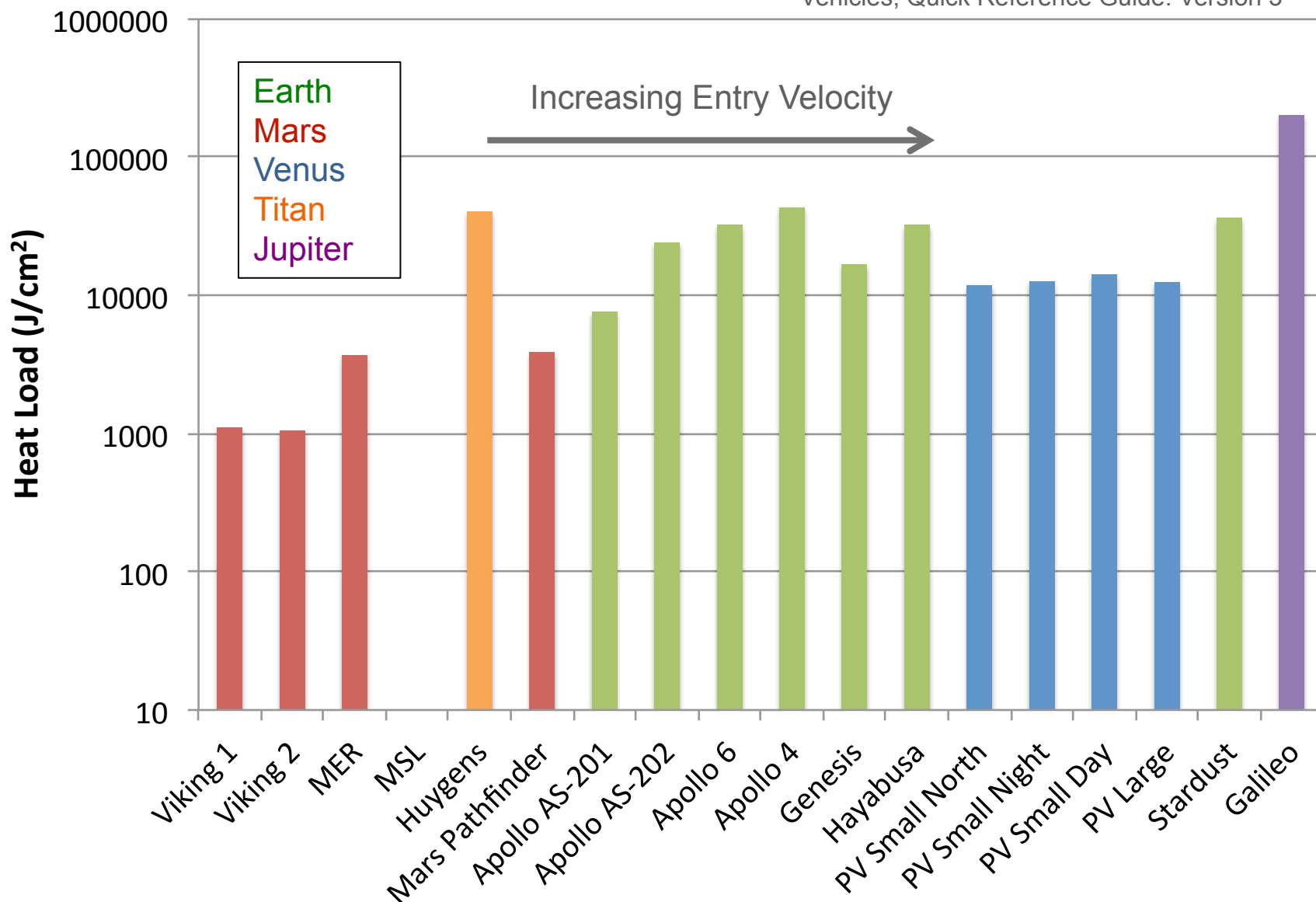


Max. Heat Flux for Select Entry Vehicles

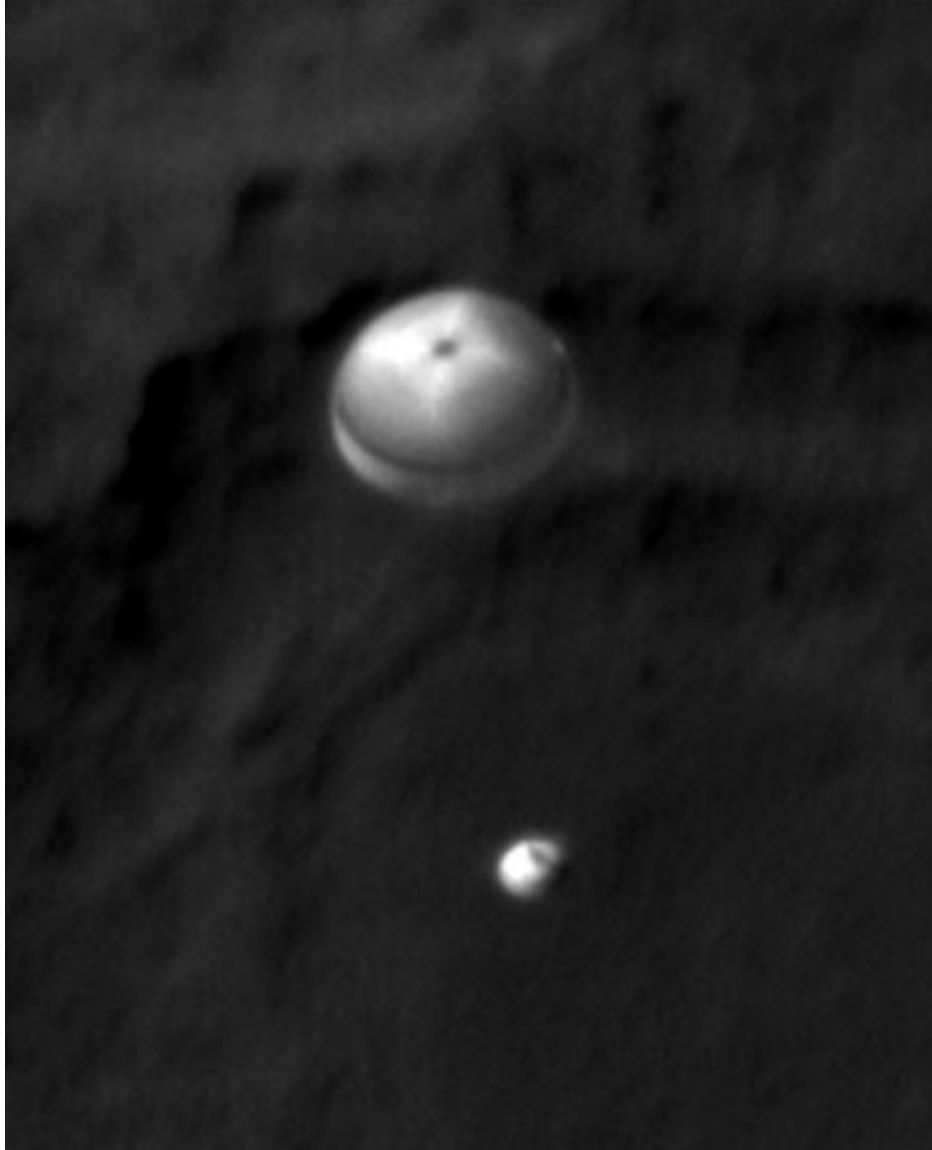


Heat Load for Select Entry Vehicles

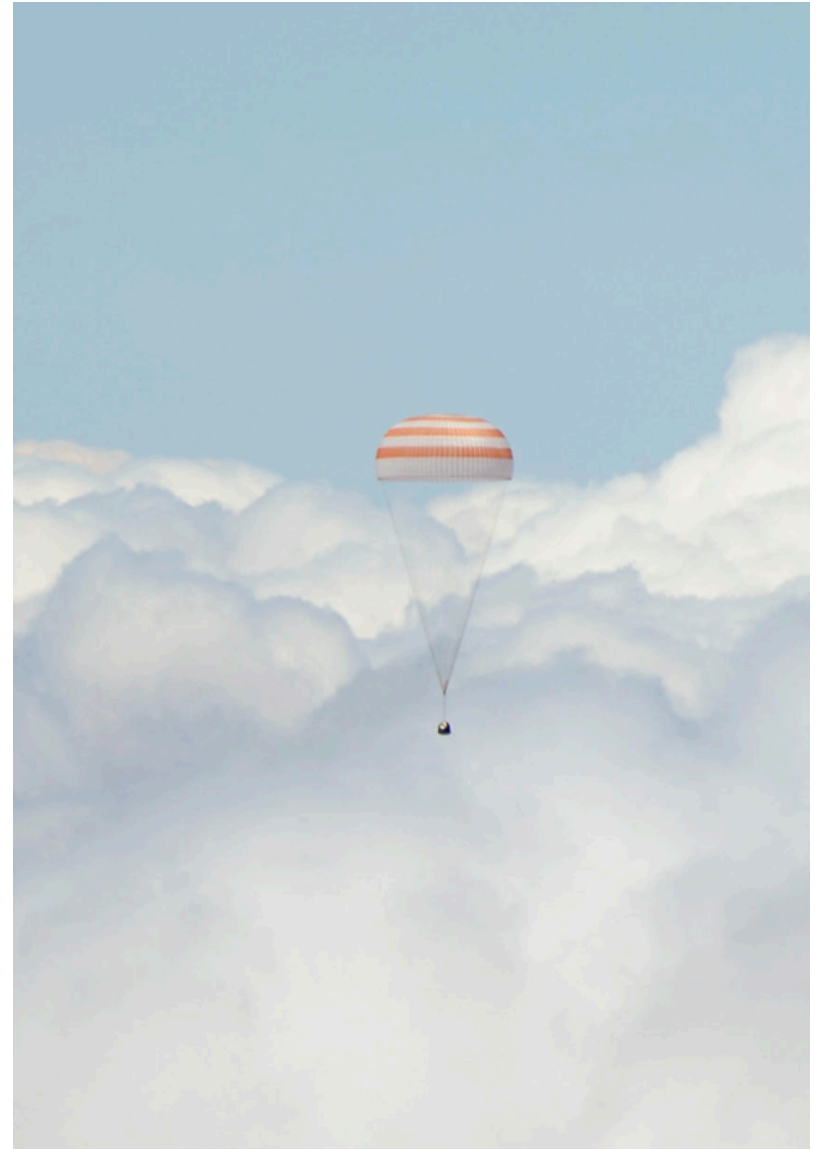
Ref. Davies, C., "Planetary Mission Entry Vehicles, Quick Reference Guide: Version 3"



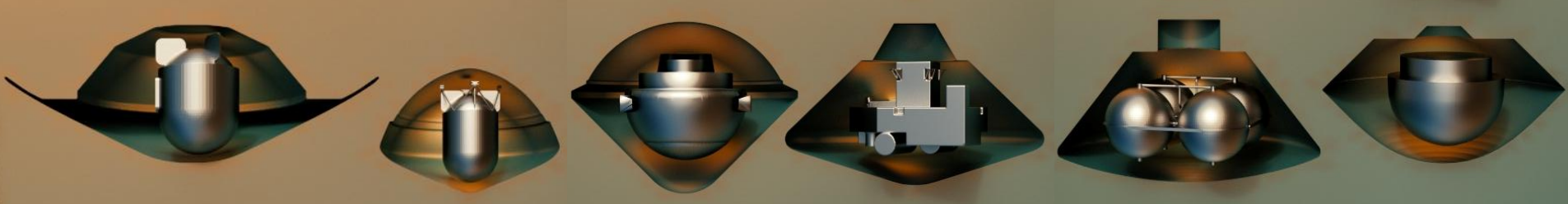
Questions/Discussion?



NASA/JPL-Caltech/Univ. of Arizona
International Planetary Probe Workshop 10 Short Course 2013



ISS Expedition 31, NASA/Bill Ingalls



Aerodynamics References



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Introduction

Blunt Body Aerodynamics¹

Entry Vehicles

CORONA Aerodynamics²⁻⁴

Early Manned Aerodynamics⁵

Apollo⁶⁻¹⁰

MPCV, Orion¹¹⁻¹⁴

Viking Aerodynamics¹⁵⁻¹⁸

Mars Pathfinder¹⁹⁻²¹

Mars Exploration Rover²²⁻²⁴

Mars Science Laboratory²⁵⁻²⁸

Mars Phoenix²⁹

Galileo³⁰

Pioneer Venus³¹

Microprobe^{32, 33}

Hayabusa (MUSES-C)

Stardust³⁴

Genesis³⁵

Huygens probe^{36, 37}

Static Aerodynamics

Newtonian Aerodynamics^{38, 39}

Modified Newtonian⁴⁰

LAURA CFD⁴¹

Shape Optimization⁴²

Aerodynamic Surfaces (Trim Tabs)⁴³⁻⁴⁵

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Dynamic Stability

Dynamic Stability Testing^{46–50}

Dynamic Stability Theory and Computation^{51–56}

Reaction Control System

Reaction Control Systems^{57–59}

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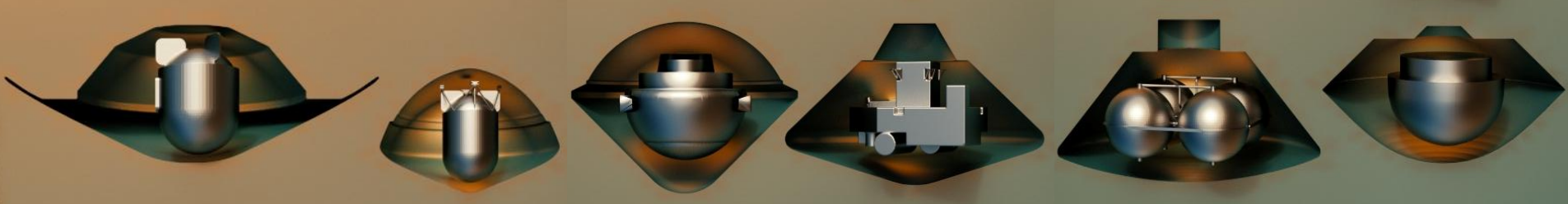
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